Contents

How to Read these Operating Instructions

□ **How to Read these Operating Instructions**

VLT® AutomationDrive FC 300 is designed to provide high shaft performance on electrical motors. Please read this manual carefully for proper use. Incorrect handling of the frequency converter may cause improper operation of the frequency converter or related equipment, shorten lifetime or cause other troubles.

These Operating Instructions will help you get started, install, program, and troubleshoot your VLT® AutomationDrive FC 300.
The VLT® AutomationDrive FC 300 comes in two shaft performance levels. FC 301 ranges from scalar (U/f) to VVC+, and FC 302 ranges from scalar (U/f) to servo performance.
These Operating Instructions cover both FC 301 and FC 302. Where information covers both series, we refer to FC 300. Otherwise, we refer specifically to either FC 301 or FC 302.

Chapter 1, **How to Read these Operating Instructions**, introduces the manual and informs you about the approvals, symbols, and abbreviations used in this literature.

Page divider for How to Read these Operating Instructions.

Chapter 2, **Safety Instructions and General Warnings**, entails instructions on how to handle the FC 300 correctly.
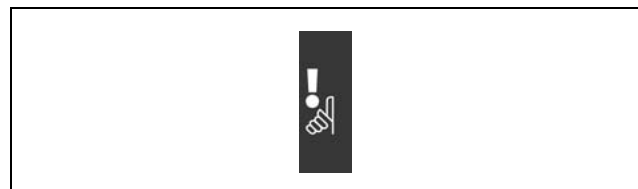
Page divider for Safety Instructions and General Warnings.

─ How to Read these Operating Instructions ─

Chapter 3, **How to Install**, guides you through mechanical and technical installation.
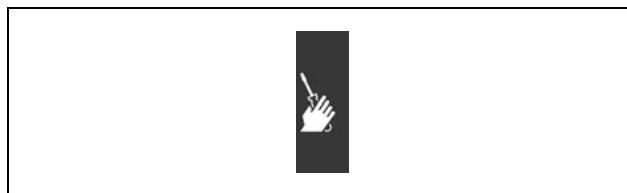
Page divider for How to Install

Chapter 4, **How to Programme**, shows you how to operate and programme the FC 300 via the Local Control Panel.
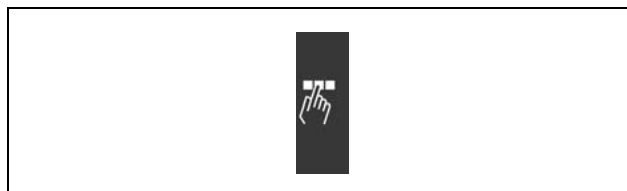
Page divider for How to Programme.

Chapter 5, **General Specifications**, entails technical data about FC 300.

Page divider for General Specifications.

Chapter 6, **Troubleshooting**, assists you in solving problems that may occur when using FC 300.

Page divider for Troubleshooting.

Available literature for FC 300

- The VLT® AutomationDrive FC 300 Operating Instructions provide the neccessary information for getting the drive up and running.
- The VLT® AutomationDrive FC 300 Design Guide entails all technical information about the drive and customer design and applications including encoder, resolver and relay options.
- The VLT® AutomationDrive FC 300 Profibus Operating Instructions provide the information required for controlling, monitoring and programming the drive via a Profibus fieldbus.
- The VLT® AutomationDrive FC 300 DeviceNet Operating Instructions provide the information required for controlling, monitoring and programming the drive via a DeviceNet fieldbus.
- The VLT® AutomationDrive FC 300 MCT 10 Operating Instructions provide information for installation and use of the software on a PC.
- The VLT® AutomationDrive FC 300 IP21 / TYPE 1 Instruction provides information for installing the IP21 / TYPE 1 option.
- The VLT® AutomationDrive FC 300 24 V DC Backup Instruction provides information for installing the 24 V DC Backup option.

Danfoss Drives technical literature is also available online at www.danfoss.com/drives.

How to Read these Operating Instructions

☐ Approvals

☐ Abbreviations

Alternating current	AC
American wire gauge	AWG
Ampere/AMP	A
Automatic Motor Adaptation	AMA
Current limit	I_{LIM}
Degrees Celcius	°C
Direct current	DC
Drive Dependent	D-TYPE
Electro Magnetic Compellability	EMC
Electronic ThermAL Relay	ETR
Frequency Converter	FC
Gram	g
Hertz	Hz
Kilohertz	kHz
Local Control Panel	LCP
Meter	m
Milli Henry Inductance	mH
Milliampere	mA
Millisecond	ms
Minute	min
Motion Control Tool	MCT
Motor Type Dependent	M-TYPE
Nanofarad	nF
Newton Meters	Nm
Nominal motor current	$I_{M,N}$
Nominal motor frequency	$f_{M,N}$
Nominal motor power	$P_{M.N}$
Nominal motor voltage	$U_{M,N}$
Parameter	par.
Protective Extra Low Voltage	PELV
Printed Circuit Board	PCB
Rated Inverter Output Current	I_{INV}
Revolutions Per Minute	RPM
Second	s
Torque limit	T_{LIM}
Volts	V

☐ Symbols

Symbols used in these Operating Instructions.

NB!:
Indicates something to be noted by the reader.

Indicates a general warning.

Indicates a high-voltage warning.

∗   Indicates default setting

Safety Instructions and General Warning

Equipment containing electrical components may not be disposed together with domestic waste.
It must be separate collected with Electrical and Electronic waste according to local and currently valid legislation.

Caution

The FC 300 AutomationDrive DC link capacitors remain charged after power has been disconnected. To avoid an electrical shock hazard, disconnect the FC 300 from the mains before carrying out maintenance. Wait at least as follows before doing service on the frequency converter:
FC 300:   0.25 – 7.5 kW   4 minutes
FC 300:   11 – 22 kW   15 minutes
Be aware that there may be high voltage on the DC link even when the LEDs are turned off.

— Safety Instructions and General Warning —

FC 300
Operating Instructions
Software version: 4.0x

These Operating Instructions can be used for all FC 300 frequency converters with software version 4.0x.
The software version number can be seen from parameter 15-43.

□ **High Voltage Warning**

The voltage of the FC 300 is dangerous whenever the converter is connected to mains. Incorrect fitting of the motor or frequency converter may cause damage to the equipment, serious injury or death. Consequently, it is essential to comply with the instructions in this manual as well as local and national rules and safety regulations.

□ **Safety Instructions**

- Make sure the FC 300 is properly connected to earth.
- Do not remove mains plugs or motor plugs while the FC 300 is connected to mains.
- Protect users against supply voltage.
- Protect the motor against overloading according to national and local regulations.
- Motor overload protection is not included in the default settings. To add this function, set parameter 1-90 *Motor thermal protection* to value *ETR trip* or *ETR warning*. For the North American market: ETR functions provide class 20 motor overload protection, in accordance with NEC.
- The earth leakage current exceeds 3.5 mA.
- The [OFF] key is not a safety switch. It does not disconnect the FC 300 from mains.

General warning

Warning:
Touching the electrical parts may be fatal - even after the equipment has been disconnected from mains.
Also make sure that other voltage inputs have been disconnected, such as load-sharing (linkage of DC intermediate circuit), as well as the motor connection for kinetic back-up.
Using VLT AutomationDrive FC 300: wait at least 15 minutes.
Shorter time is allowed only if indicated on the nameplate for the specific unit.

Leakage Current
The earth leakage current from the FC 300 exceeds 3.5 mA. To ensure that the earth cable has a good mechanical connection to the earth connection (terminal 95), the cable cross section must be at least 10 mm^2 or 2 times rated earth wires terminated separately.

Residual Current Device
This product can cause a D.C. current in the protective conductor. Where a residual current device (RCD) is used for extra protection, only an RCD of Type B (time delayed) shall be used on the supply side of this product. See also RCD Application Note MN.90.GX.02.
Protective earthing of the FC 300 and the use of RCD's must always follow national and local regulations.

— Safety Instructions and General Warning —

□ **Before Commencing Repair Work**

1. Disconnect FC 300 from mains
2. Disconnect DC bus terminals 88 and 89
3. Wait for discharge of the DC-link. See period of time on the warning label.
4. Remove motor cable

□ **Avoid Unintended Start**

While FC 300 is connected to mains, the motor can be started/stopped using digital commands, bus commands, references or via the Local Control Panel (LCP).

- Disconnect the FC 300 from mains whenever personal safety considerations make it necessary to avoid unintended start.
- To avoid unintended start, always activate the [OFF] key before changing parameters.
- An electronic fault, temporary overload, a fault in the mains supply, or lost motor connection may cause a stopped motor to start. FC 300 with Safe Stop (i.e. FC301 in A1 enclosure and FC302) provides a certain degree of protection against such unintended start, if the Safe Stop Terminal 37 is on low voltage level or disconnected.

□ **Safe Stop of FC 300**

The FC 302, and also the FC301 in A1 enclosure, can perform the safety function *Safe Torque Off* (As defined by draft CD IEC 61800-5-2) or *Stop Category 0* (as defined in EN 60204-1).

FC 301 A1 enclosure: When Safe Stop is included in the drive position 18 of Type Code must be either T or U. If position 18 is B or X Safe Stop Terminal 37 is not included!
Example:
Type Code for FC 301 A1 with Safe Stop:
FC-301PK75T4**Z20**H4**T**GCXXXSXXXXA0BXCXXXXD0

It is designed and approved suitable for the requirements of Safety Category 3 in EN 954-1. This functionality is called Safe Stop. Prior to integration and use of Safe Stop in an installation, a thorough risk analysis on the installation must be carried out in order to determine whether the Safe Stop functionality and safety category are appropriate and sufficient. In order to install and use the Safe Stop function in accordance with the requirements of Safety Category 3 in EN 954-1, the related information and instructions of the FC 300 Design Guide MG.33.BX.YY must be followed! The information and instructions of the Operating Instructions are not sufficient for a correct and safe use of the Safe Stop functionality!

— Safety Instructions and General Warning —

□ **Safe Stop Installation (FC 302 and FC 301 - A1 enclosure only)**

To carry out an installation of a Category 0 Stop (EN60204) in conformance with Safety Category 3 (EN954-1), follow these instructions:

1. The bridge (jumper) between Terminal 37 and 24 V DC must be removed. Cutting or breaking the jumper is not sufficient. Remove it entirely to avoid short-circuiting. See jumper on illustration.

2. Connect terminal 37 to 24 V DC by a short-circuit protected cable. The 24 V DC voltage supply must be interruptible by an EN954-1 Category 3 circuit interrupt device. If the interrupt device and the frequency converter are placed in the same installation panel, you can use a regular cable instead of a protected one.
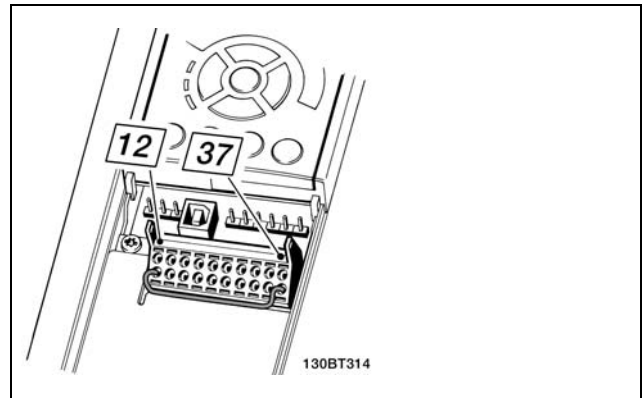
Bridge jumper between terminal 37 and 24 VDC

The illustration below shows a Stopping Category 0 (EN 60204-1) with safety Cat. 3 (EN 954-1). The circuit interrupt is caused by an opening door contact. The illustration also shows how to connect a non-safety related hardware coast.
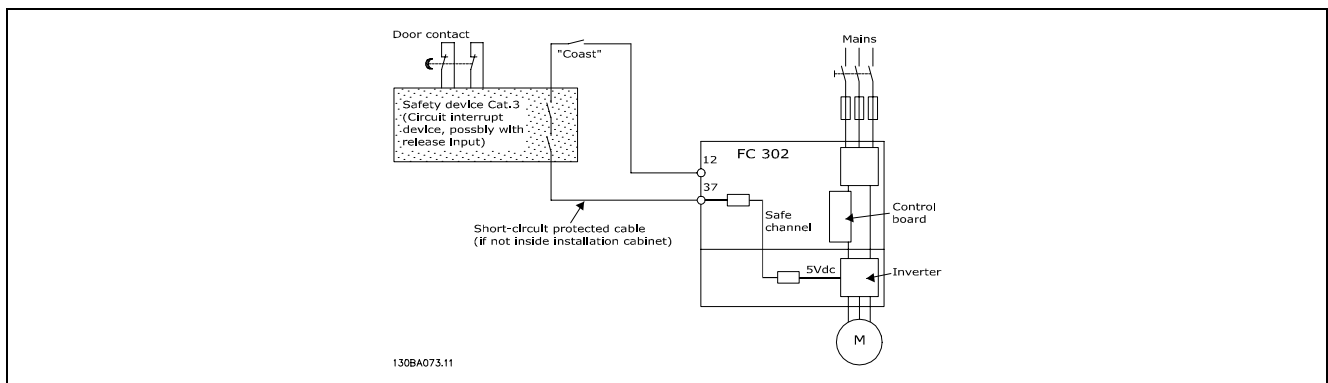
Illustration of the essential aspects of an installation to achieve a Stopping Category 0 (EN 60204-1) with safety Cat. 3 (EN 954-1).

⚠ **IT Mains**
Do not connect 400 V frequency converters with RFI-filters to mains supplies with a voltage between phase and earth of more than 440 V.
For IT mains and delta earth (grounded leg), mains voltage may exceed 440 V between phase and earth.

Par. 14-50 *RFI 1* can on FC 302 be used to disconnect the internal RFI capacitiors from the RFI filter to ground. If this is done it will reduce the RFI performance to A2 level.

How to Install
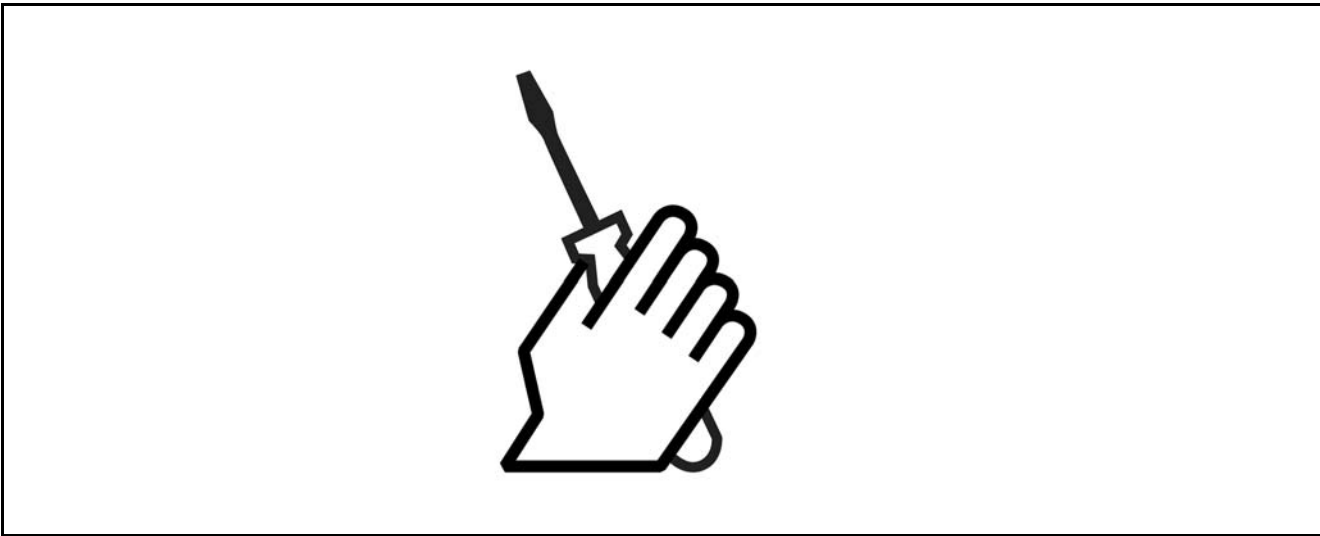
☐ **About How to Install**

This chapter covers mechanical and electrical installations to and from power terminals and control card terminals.

Electrical installation of *options* is described in the corresponding Instructions and Design Guide MG33.BX.YY.

☐ **How to Get Started**

FC 300 AutomationDrive is designed to achieve a quick and EMC-correct installation by following the steps described below.

Frame size is depending on enclosure type, power range and mains voltage

Read the safety instructions before installing the unit.

Mechanical Installation

• Mechanical mounting

Electrical Installation

• Connection to Mains and Protecting Earth
• Motor connection and cables
• Fuses and circuit breakers
• Control terminals - cables

Quick setup

• Local Control Panel, LCP
• Automatic Motor Adaptation, AMA
• Programming
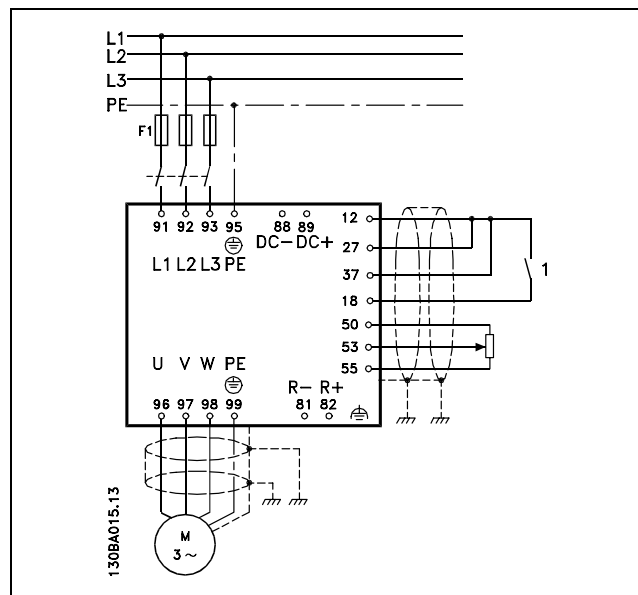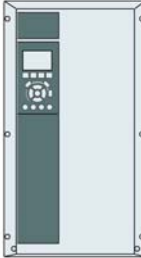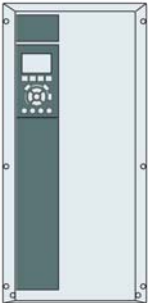
Diagram showing basic installation including mains, motor, start/stop key, and potentiometer for speed adjustment.

Enclosure type		A1	A2	A3	A5	B1	B2
		130BA339.10	130BA340.10	130BA341.10	130BA342.10	130BA343.10	130BA344.10
Enclosure protection	IP	20/21	20/21	20/21	55	21/55	21/55
	NEMA	Chassis/Type1	Chassis/ Type1	Chassis/ Type1	Type12	Type1/Type12	Type1/Type12
Rated power		0.25 – 1.5 kW (200-240 V) 0.37 – 1.5 kW (380-480 V)	0.25-2.2 kW (200 – 240 V) 0.37-4.0 kW (380-480/500V)	3.0-3.7 kW (200-240 V) 5.5-7.5 kW (380-480/ 500 V) 0.75-7.5 kW (550-600V)	0.25-3.7 kW (200-240 V) 0.37-7.5 kW (380-480/ 500 V) 0.75-7.5 kW (550-600 V)	5.5 kW (200-240 V) 11-15 kW (380-500 V)	7.5-11 kW (200-250 V) 18.5-22 kW (380-500 V)

□ **Accessory Bag**
Find the following parts included in the FC
300 Accessory Bag.

FC 301/FC 302
Frame sizes A1, A2 and A3
IP20/Chassis

FC 301/FC 302
Frame size A5
IP55/Type12

FC 301/FC 302
Frame sizes B1 and B2
IP21/IP55/Type1/Type12

1 + 2 only available in units with brake chopper FC 301 without Safe Stop. Only one relay connector is included for FC 301 units. For DC link connection (Load sharing) the connector 1 can be ordered separately (Code no 130B1064)

An eight pole connector included in accessory
bag for FC 301 without Safe Stop.

□ Mechanical Installation

□ Mechanical mounting

FC 300 IP20 Frame sizes A1, A2 and A3 allows side-by-side installation. Due to cooling conditions, there must be a minimum of 100 mm free air passage above and below the FC 300.

If the IP 21 Enclosure kit (130B1122 or 130B1123)
is used there must be a clearance between
the drives of min 50 mm.

1. Drill holes in accordance with the measurements given.
2. You must provide screws suitable for the surface on which you want to mount the FC 300. Retighten all four screws.
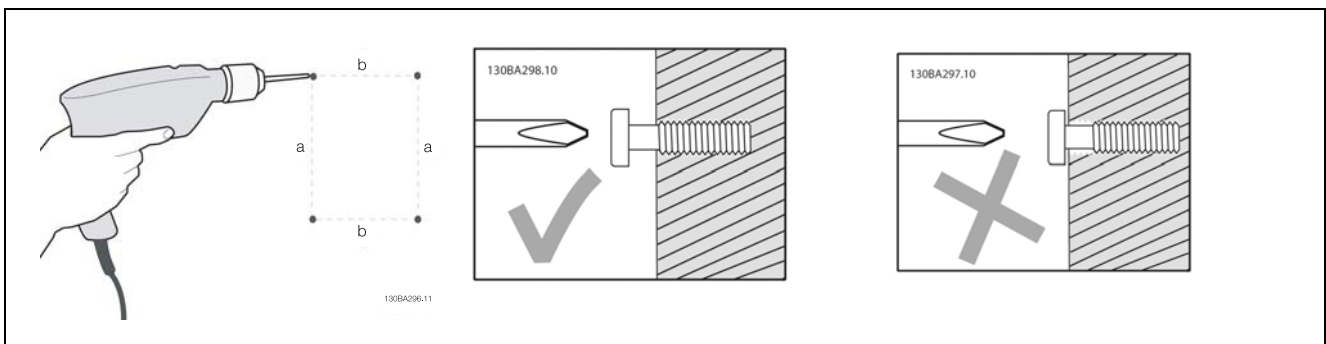
Mounting frame sizes A1, A2 and A3:
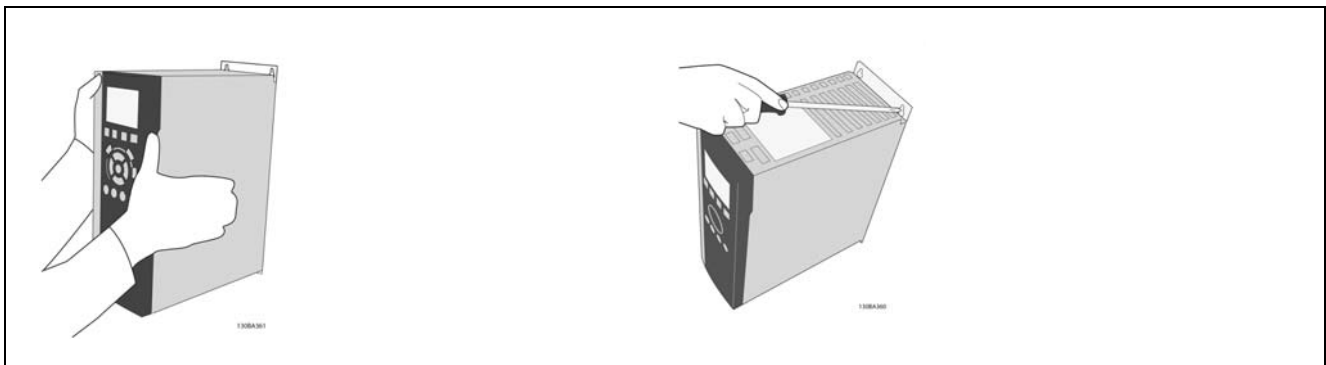
— How to Install —

Mounting frame sizes A5, B1 and B2:

The back wall must always be solid for optimum cooling.
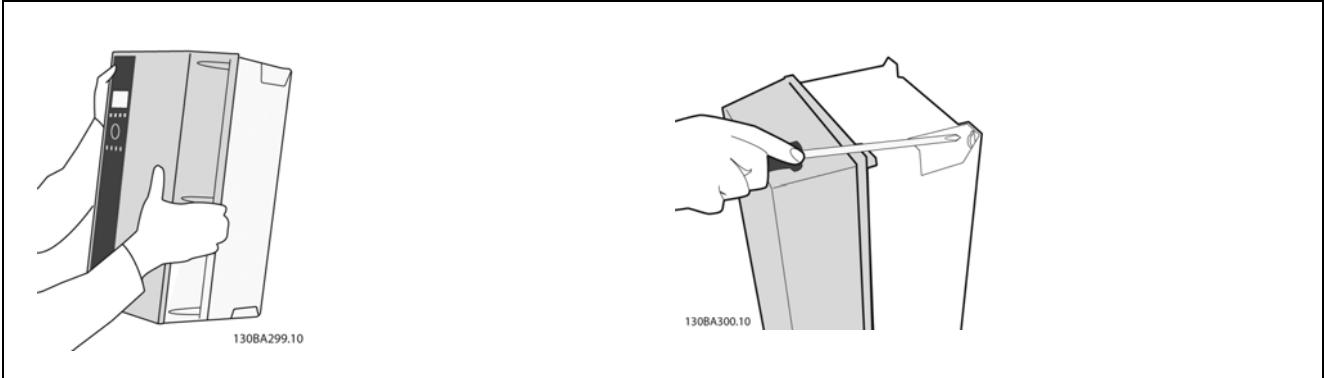
Mounting frame sizes A5, B1, and B2 on a none solid back wall, the drive must be provided with a back plate A due to insufficient cooling air over the heat sink.
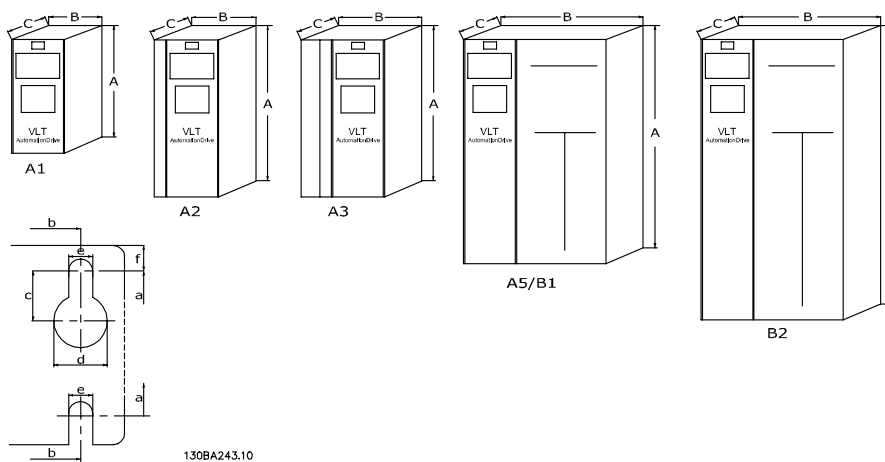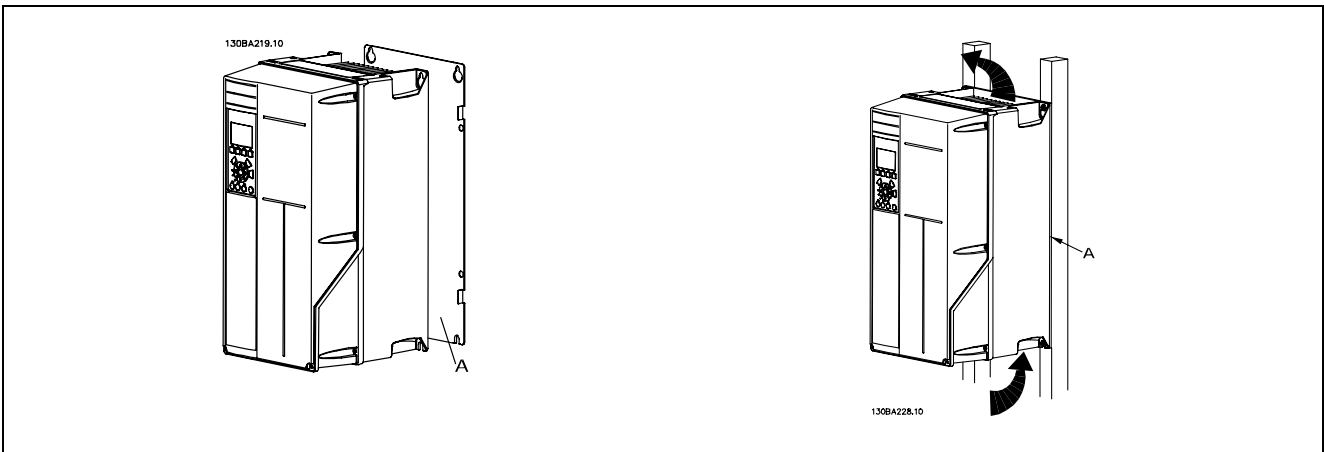
— How to Install —

Mechanical dimensions										
		Frame size A1		Frame size A2		Frame size A3		Frame size A5	Frame size B1	Frame size B2
		0.25–1.5 kW (200-240 V) 0.37-1.5 kW (380-480 V)		0.25-2.2 kW (200-240 V) 0.37-4.0 kW (380-480 V)		3.0-3.7 kW (200-240 V) 5.5-7.5 kW (380-480/ 500 V) 0.75-7.5 kW (525-600 V)		0.25-3.7 kW (200-240 V) 0.37-7.5 kW (380-480 V)	5.5 kW (200-240 V) 11-15 kW (380-480/500 V)	7.5-11 kW (200-240 V) 18.5-22 kW (380-500 V)
IP NEMA		20 Chassis	21 Type1	20 Chassis	21 Type1	20 Chassis	21 Type1	55 Type12	21/ 55 Type1/Type12	21/55 Type1/Type12
Height										
Height of back plate	A	200 mm		268 mm	375 mm	268 mm	375 mm	420 mm	480 mm	650 mm
Height with de-coupling plate	A	315.95	-	373.79	-	373.79	-	-	-	-
Distance between mounting holes	a	190 mm		257 mm	350 mm	257 mm	350 mm	402 mm	454 mm	624 mm
Width										
Width of back plate	B	75 mm		90 mm	90 mm	130 mm	130 mm	242 mm	242 mm	242 mm
Width of back plate with one C option	B			130 mm	130 mm	170 mm	170 mm	242 mm	242 mm	242 mm
Width of back plate with two C options	B			150 mm	150 mm	190 mm	190 mm	242 mm	242 mm	242 mm
Distance between mounting holes	b	60 mm		70 mm	70 mm	110 mm	110 mm	215 mm	210 mm	210 mm
Depth										
Depth without option A/B	C	205 mm		205 mm	205 mm	205 mm	205 mm	195 mm	260 mm	260 mm
With option A/B	C	220 mm		220 mm	220 mm	220 mm	220 mm	195 mm	260 mm	260 mm
Without option A/B	D	207 mm			207 mm		207 mm			
With option A/B	D	222 mm			222 mm		222 mm			
Screw holes										
	c	6.0 mm		8.0 mm	8.0 mm	8.0 mm	8.0 mm	8.25 mm	12 mm	12 mm
	d	ø8 mm		ø11 mm	ø11 mm	ø11 mm	ø11 mm	ø12 mm	ø19 mm	ø19 mm
	e	ø5 mm		ø5.5 mm	ø5.5 mm	ø5.5 mm	ø5.5 mm	ø6.5 mm	ø9 mm	ø9 mm
	f	5 mm		9 mm	9 mm	9 mm	9 mm	9 mm	9 mm	9 mm
Max weight		2.7 kg		4.9 kg	5.3 kg	6.6 kg	7.0 kg	13.5/14.2 kg	23 kg	27 kg

□ Electrical Installation

NB!:
Cables General
All cabling must comply with national and local regulations on cable cross-sections and ambient temperature. Copper (60/75°C) conductors recommended.

Aluminium Conductors

Aluminium conductors are not recommended. Terminals can accept aluminium conductors but the conductor surface has to be clean and the oxidation must be removed and sealed by neutal acid free Vaseline grease before the conductor is connected.

Furthermore the terminal screw must be retightened after two days due to softness of the aluminium. It is crucial to keep the connection a gas tight joint, otherwise the aluminium surface will oxidize again.

Tightening-up Torque		
FC size	Cable for:	Tightening up torque
0.25-7.5 kW (A1, A2, A3 and A5)	Line, Brake resistor, load sharing, Motor cables	0.5-0.6 Nm
11-15 kW (B1)	Line, Brake resistor, load sharing, Motor cables	1.8 Nm
	Relay	0.5-0.6 Nm
	Earth	2-3 Nm
18.5-22 kW (B2)	Line, Brake resistor, load sharing cables	1.8 Nm
	Motor cables	1.8 Nm
	Relay	0.5-0.6 Nm
	Earth	2-3 Nm

□ Removal of Knockouts for Extra Cables

1. Remove cable entry from the frequency converter (Avoiding foreign parts falling into the frequency converter when removing knockouts)
2. Cable entry has to be supported around the knockout you intend to remove.
3. The knockout can now be removed with a strong mandrel and a hammer.
4. Remove burrs from the hole.
5. Mount Cable entry on frequency converter.

□ Connection to Mains and Earthing

NB!:
The plug connector for power can be removed on FC 302 up to 7.5 kW.

1. Fit the two screws in the de-coupling plate, slide it into place and tighten the screws.
2. Make sure the FC 300 is properly earthed. Connect to earth connection (terminal 95). Use screw from the accessory bag.
3. Place plug connector 91(L1), 92(L2), 93(L3) from the accessory bag onto the terminals labelled MAINS at the bottom of FC 300.
4. Attach mains wires to the mains plug connector.
5. Relive the cable with the supporting enclosed brackets.

NB!:
Check that mains voltage corresponds to the mains voltage of the FC 300 name plate.

IT Mains
Do not connect 400 V frequency converters with RFI-filters to mains supplies with a voltage between phase and earth of more than 440 V.

The earth connection cable cross section must be at least 10 mm^2 or 2 x rated mains wires terminated separately according to EN 50178.

The mains connection is fitted to the main switch if this is included.
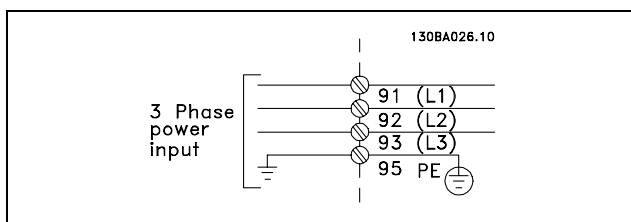
— How to Install —

Mains connection for A1, A2 and A3 frame sizes:

NB!:
The plug connector for power can be removed.

130BA261.10
130BA262.10
130BA263.10
130BA264.10
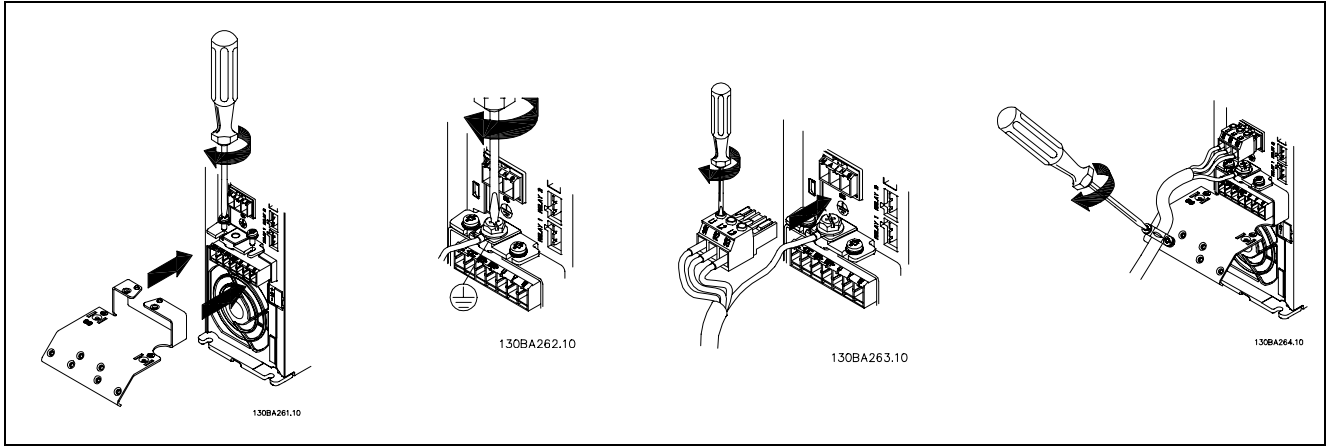
Mains connector A5 (IP 55) Enclosure

130BT336
130BT335
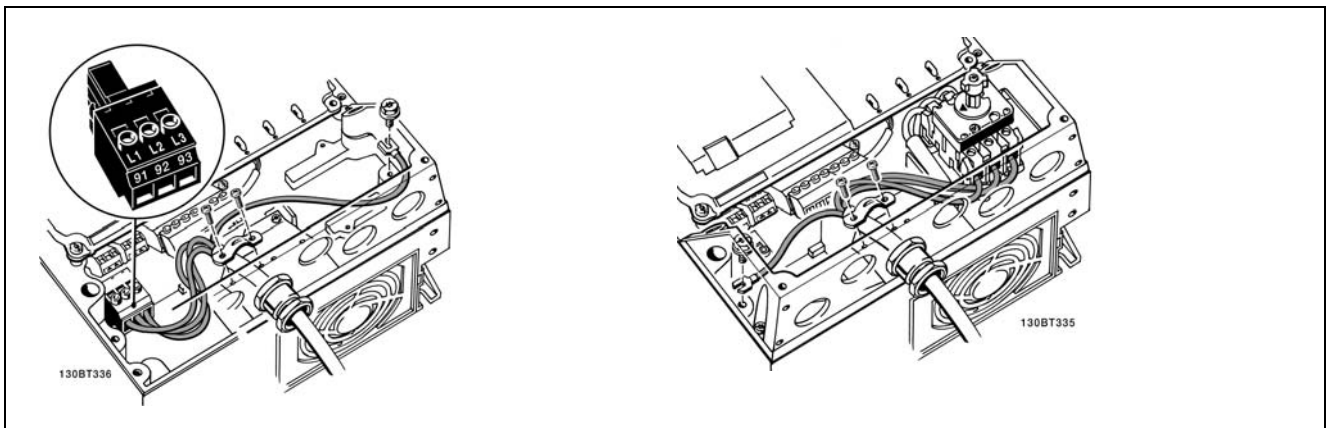
When disconnector is used (A5 enclosure) the PE must be mounted on the left side of the drive.

Mains connection B1 and B2 (IP 21/NEMA Type1 and IP 55/NEMA Type12) Enclosures

130BT332
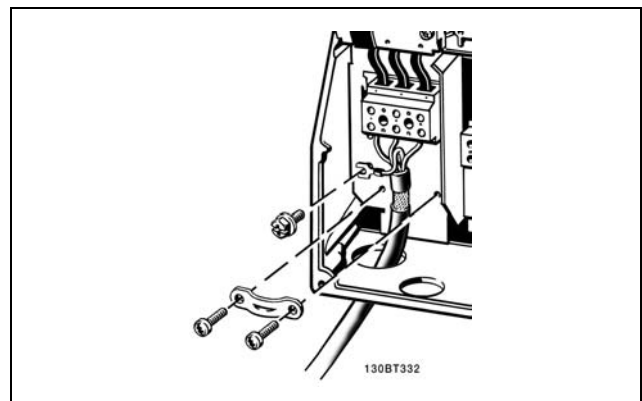
Usually the power cables for mains are unshielded cables.

─ How to Install ─

☐ **Motor Connection**

NB!:
Motor cable must be screened/armoured. If an unscreened/unarmoured cable is used, some EMC requirements are not complied with. For more information, see *EMC specifications* in the *VLT AutomationDrive FC 300 Design Guide*.

See section General Specifications for correct dimensioning of motor cable cross-section and length.

- Use a screened/armoured motor cable to comply with EMC emission specifications. If an unscreened/unarmoured cable is used, some EMC requirements are not complied with. For more information, see EMC specifications in the VLT AutomationDrive FC 300 Design Guide.
- Keep the motor cable as short as possible to reduce the noise level and leakage currents.
- Connect the motor cable screen to both the decoupling plate of the FC 300 and to the metal housing of the motor.
- Make the screen connections with the largest possible surface area (cable clamp). This is done by using the supplied installation devices in the FC 300.
- Screening of cables: Avoid installation with twisted screen ends (pigtails). They spoil the screening effect at higher frequencies. If it is necessary to break the screen to install a motor isolator or motor contactor, the screen must be continued at the lowest possible HF impedance.
- If it is necessary to split the screen to install a motor isolator or motor relay, the screen must be continued with the lowest possible HF impedance.

Screening of cables: Avoid installation with twisted screen ends (pigtails). They spoil the screening effect at higher frequencies. If it is necessary to break the screen to install a motor isolator or motor contactor, the screen must be continued at the lowest possible HF impedance.

Cable-length and cross-section: The frequency converter has been tested with a given length of cable and a given cross-section of that cable. If the cross-section is increased, the cable capacitance - and thus the leakage current - may increase, and the cable length must be reduced correspondingly.

Switching frequency: When frequency converters are used together with LC filters to reduce the acoustic noise from a motor, the switching frequency must be set according to the LC filter instruction in Par. 14-01.

1. Fasten decoupling plate to the bottom of FC 300 with screws and washers from the accessory bag.
2. Attach motor cable to terminals 96 (U), 97 (V), 98 (W).
3. Connect to earth connection (terminal 99) on decoupling plate with screws from the accessory bag.
4. Insert plug connectors 96 (U), 97 (V), 98 (W) (up to 7.5 kW) and motor cable to terminals labelled MOTOR.
5. Fasten screened cable to decoupling plate with screws and washers from the accessory bag.
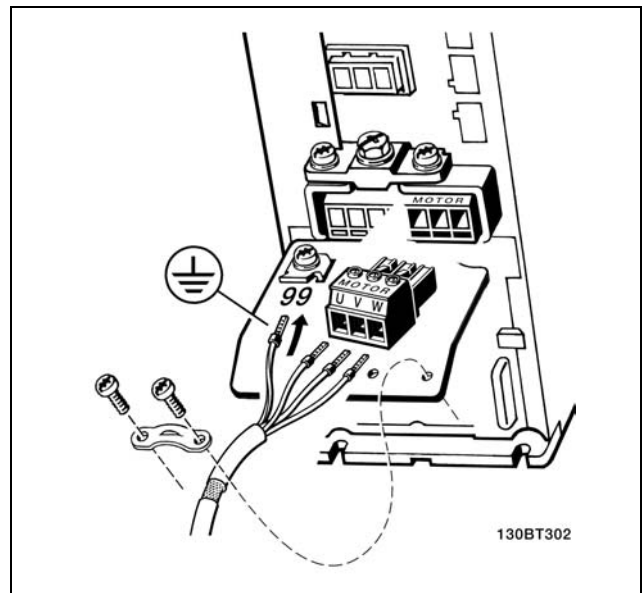
Motor connection ≤ 7.5 kW IP 20 (A1, A2 and A3 enclosures)

— How to Install —

Motor connection ≤ 7.5 kW IP 55 / NEMA type 12
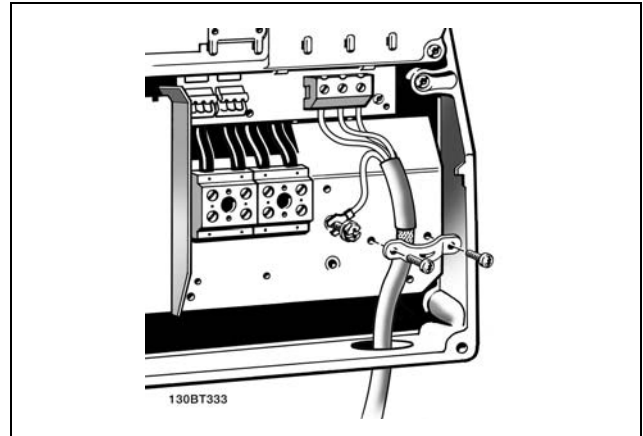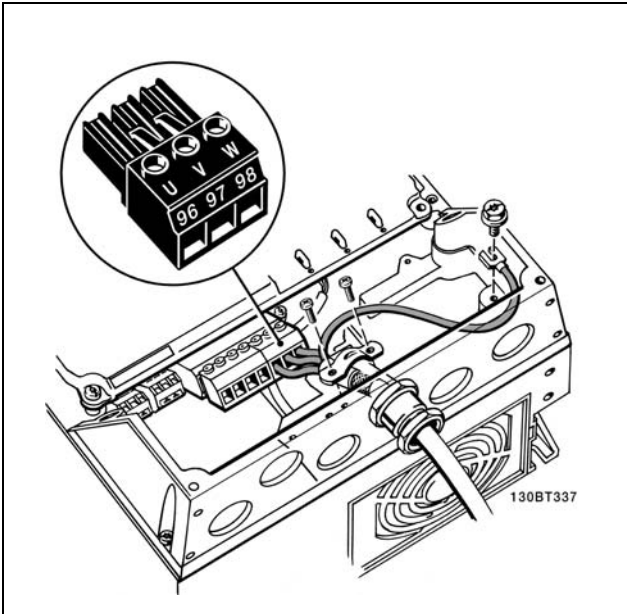
Motor connection 11-22 kW IP 21 / NEMA type 1, IP55 / NEMA type 12 (B1 and B2 enclosures)

All types of three-phase asynchronous standard motors can be connected to the FC 300. Normally, small motors are star-connected (230/400 V, △/Y). Large motors are normally delta-connected (400/690 V, △/Y). Refer to the motor name plate for correct connection mode and voltage.

No.	96	97	98	99	
	U	V	W	PE[1]	Motor voltage 0-100% of mains voltage. 3 wires out of motor
	U1 W2	V1 U2	W1 V2	PE[1]	Delta-connected 6 wires out of motor
	U1	V1	W1	PE[1]	Star-connected U2, V2, W2 U2, V2 and W2 to be interconnected separately.

[1] Protected Earth Connection
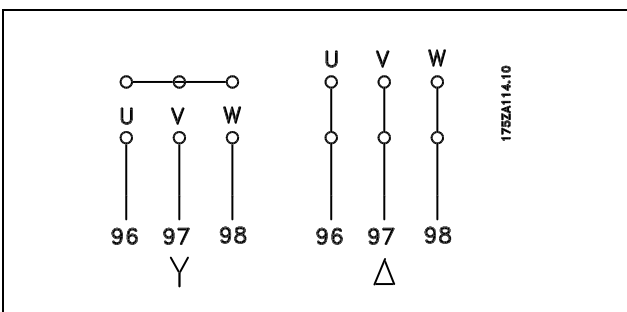
— How to Install —

☐ **Fuses**

Branch circuit protection:

In order to protect the installation against electrical and fire hazard, all branch circuits in an installation, switch gear, machines etc., must be shortcircuit and overcurrent protected according to the national/international regulations.

Short circuit protection:

The frequency converter must be protected against short-circuit to avoid electrical or fire hazard. Danfoss recommends using the fuses mentioned below to protect service personnel or other equipment in case of an internal failure in the drive. The frequency converter provides full short circuit protection in case of a short-circuit on the motor output.

Over current protection:

Provide overload protection to avoid fire hazard due to overheating of the cables in the installation. The frequency converter is equipped with an internal over current protection that can be used for upstream overload protection (UL-applications excluded). See par. 4-18. Moreover, fuses or circuit breakers can be used to provide the over current protection in the installation. Over current protection must always be carried out according to national regulations.

Fuses must be designed for protection in a circuit capable of supplying a maximum of 100,000 A_{rms} (symmetrical), 500 V maximum.

Non UL compliance

If UL/cUL is not to be complied with, we recommend using the following fuses, which will ensure compliance with EN50178:
In case of malfunction, not following the recommendation may result in unnecessary damage of the frequency converter.

FC 30X	Max. fuse size	Voltage	Type
K25-K75	10A[1)	200-240 V	type gG
1K1-2K2	20A[1)	200-240 V	type gG
3K0-3K7	32A[1)	200-240 V	type gG
K37-1K5	10A[1)	380-500 V	type gG
2K2-4K0	20A[1)	380-500 V	type gG
5K5-7K5	32A[1)	380-500 V	type gG
11K	63A[1)	380-500 V	type gG
15K	63A[1)	380-500 V	type gG
18K	63A[1)	380-500 V	type gG
22K	80A[1)	380-500 V	type gG

1) Max. fuses - see national/international regulations for selecting an applicable fuse size.

UL Compliance

200-240 V

FC 30X	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K25-K75	KTN-R10	JKS-10	JJN-10	5017906-010	KLN-R10	ATM-R10	A2K-10R
1K1-2K2	KTN-R20	JKS-20	JJN-20	5017906-020	KLN-R20	ATM-R20	A2K-20R
3K0-3K7	KTN-R30	JKS-30	JJN-30	5012406-032	KLN-R30	ATM-R30	A2K-30R

— How to Install —

380-500 V, 525-600 V

FC 30X	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K37-1K5	KTS-R10	JKS-10	JJS-10	5017906-010	KLS-R10	ATM-R10	A6K-10R
2K2-4K0	KTS-R20	JKS-20	JJS-20	5017906-020	KLS-R20	ATM-R20	A6K-20R
5K5-7K5	KTS-R30	JKS-30	JJS-30	5012406-032	KLS-R30	ATM-R30	A6K-30R
11K	KTS-R40	JKS-40	JJS-40	5014006-040	KLS-R40		A6K-40R
15K	KTS-R50	JKS-50	JJS-50	5014006-050	KLS-R50		A6K-50R
18K	KTS-R60	JKS-60	JJS-60	5014006-063	KLS-R60		A6K-60R
22K	KTS-R80	JKS-80	JJS-80	5014006-100	KLS-R80		A6K-80R

KTS-fuses from Bussmann may substitute KTN for 240 V frequency converters.
FWH-fuses from Bussmann may substitute FWX for 240 V frequency converters.
KLSR fuses from LITTEL FUSE may substitute KLNR fuses for 240 V frequency converters.
L50S fuses from LITTEL FUSE may substitute L50S fuses for 240 V frequency converters.
A6KR fuses from FERRAZ SHAWMUT may substitute A2KR for 240 V frequency converters.
A50X fuses from FERRAZ SHAWMUT may substitute A25X for 240 V frequency converters.

— How to Install —

□ **Access to Control Terminals**

All terminals to the control cables are located underneath the terminal cover on the front of the frequency converter. Remove the terminal cover by means of a screwdriver (see illustration).
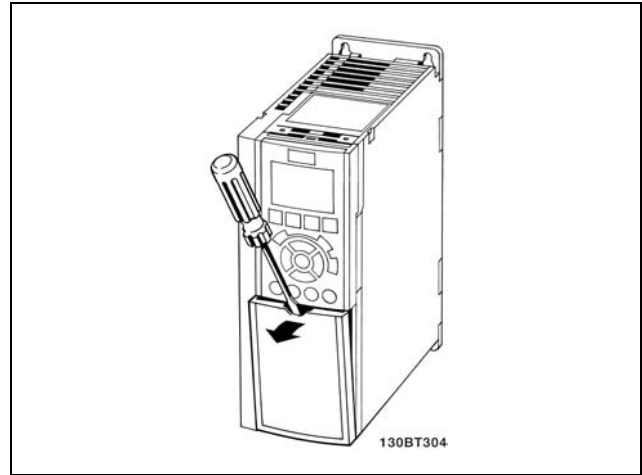
A1, A2 and A3 enclosures
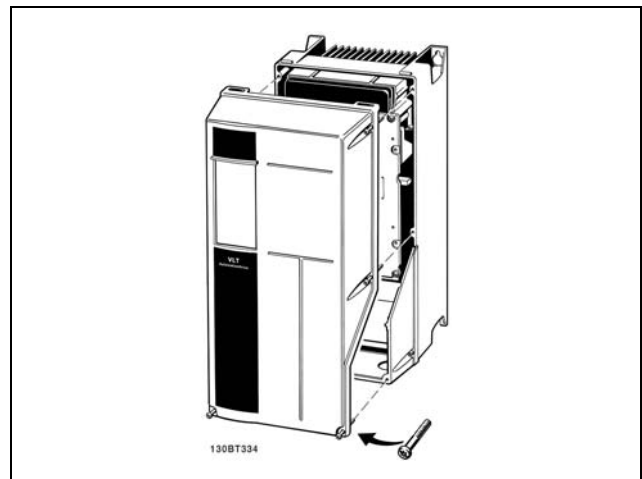
A5, B1 and B2 enclosures

□ **Electrical Installation, Control Terminals**

To mount the cable to the terminal:

1. Strip isolation of 9-10 mm
2. Insert a screw driver[1] in the square hole.
3. Insert the cable in the adjacent circular hole.
4. Remove the screw driver. The cable is now mounted to the terminal.
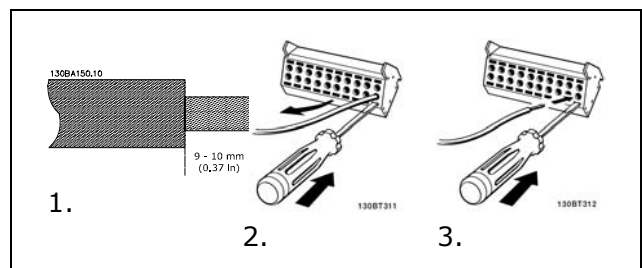
To remove the cable from the terminal:

1. Insert a screw driver[1] in the square hole.
2. Pull out the cable.

[1] Max. 0.4 x 2.5 mm

24
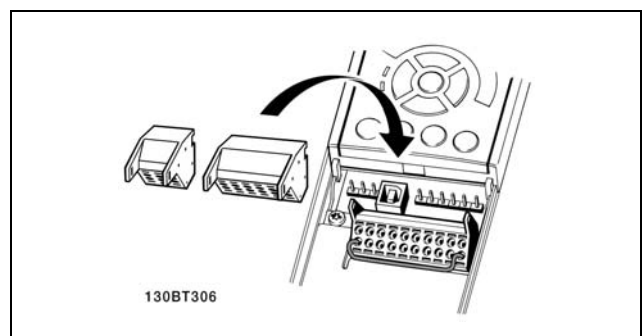
— How to Install —

Assembling of IP55 / NEMA TYPE 12 (A5 housing) with mains disconnector
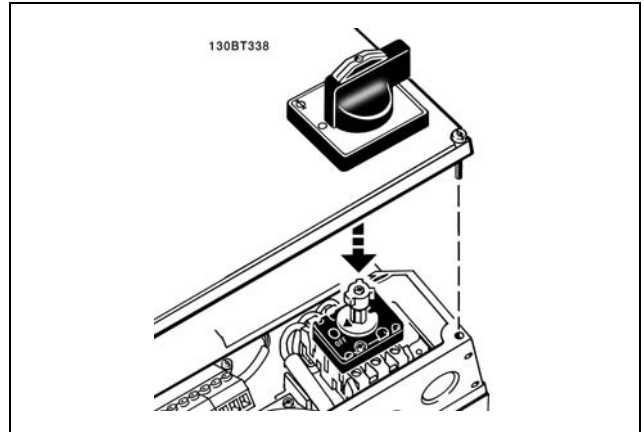
Connection Examples

Start/Stop
Terminal 18 = Par. 5-10 [8] *Start*
Terminal 27 = Par. 5-12 [0] *No operation*
(Default *coast inverse*)
Terminal 37 = Safe stop (FC 302 and FC 301 A1 only)
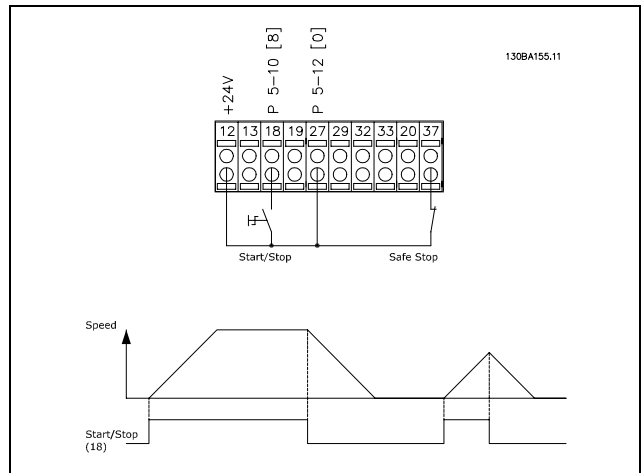
─ How to Install ─

☐ **Pulse Start/Stop**

Terminal 18 = Par. 5-10 [9] *Latched start*
Terminal 27= Par. 5-12 [6] *Stop inverse*
Terminal 37 = Safe stop (FC 302 and FC 301 A1 only!)
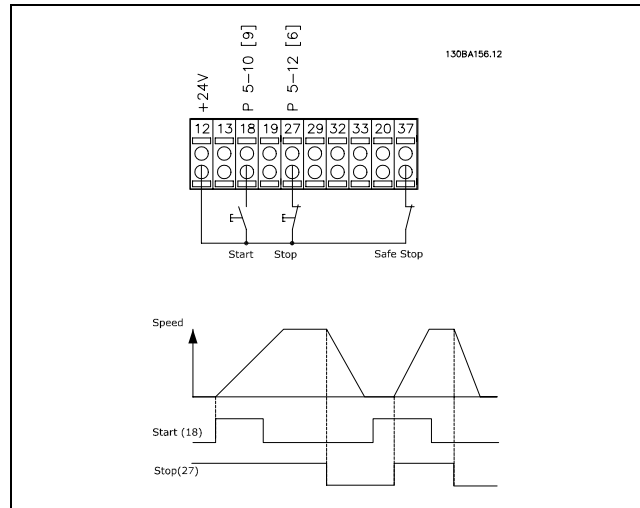
☐ **Speed Up/Down**

Terminals 29/32 = Speed up/down.

Terminal 18 = Par. 5-10 [9] *Start*(default)
Terminal 27 = Par. 5-12 [19] *Freeze reference*
Terminal 29 = Par. 5-13 [21] *Speed up*
Terminal 32 = Par. 5-14 [22] *Speed down*

Note: Terminal 29 only in FC 302.
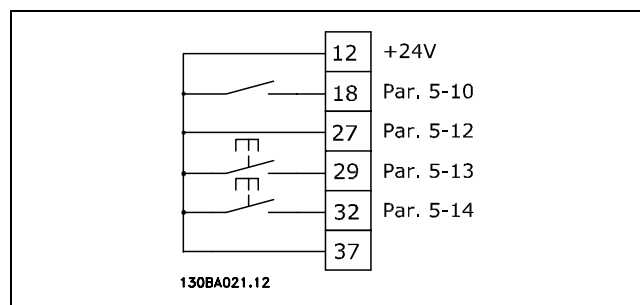
☐ **Potentiometer Reference**

Voltage reference via a potentiometer.

Reference Resource 1 = [1] *Analogue input 53* (default)
Terminal 53, Low Voltage = 0 Volt
Terminal 53, High Voltage = 10 Volt
Terminal 53, Low Ref./Feedback = 0 RPM
Terminal 53, High Ref./Feedback = 1500 RPM
Switch S201 = OFF (U)
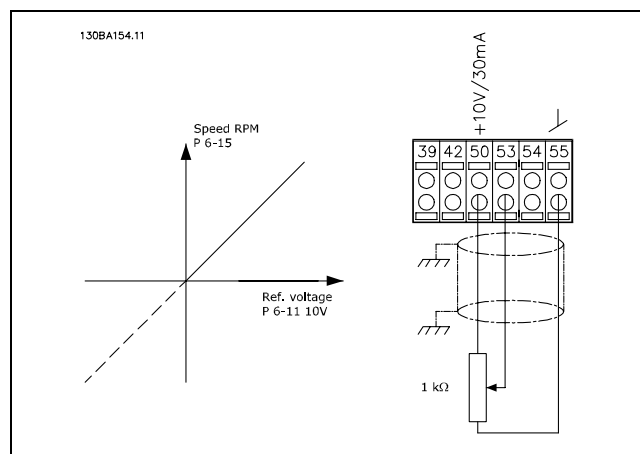
— How to Install —

□ Electrical Installation, Control Cables
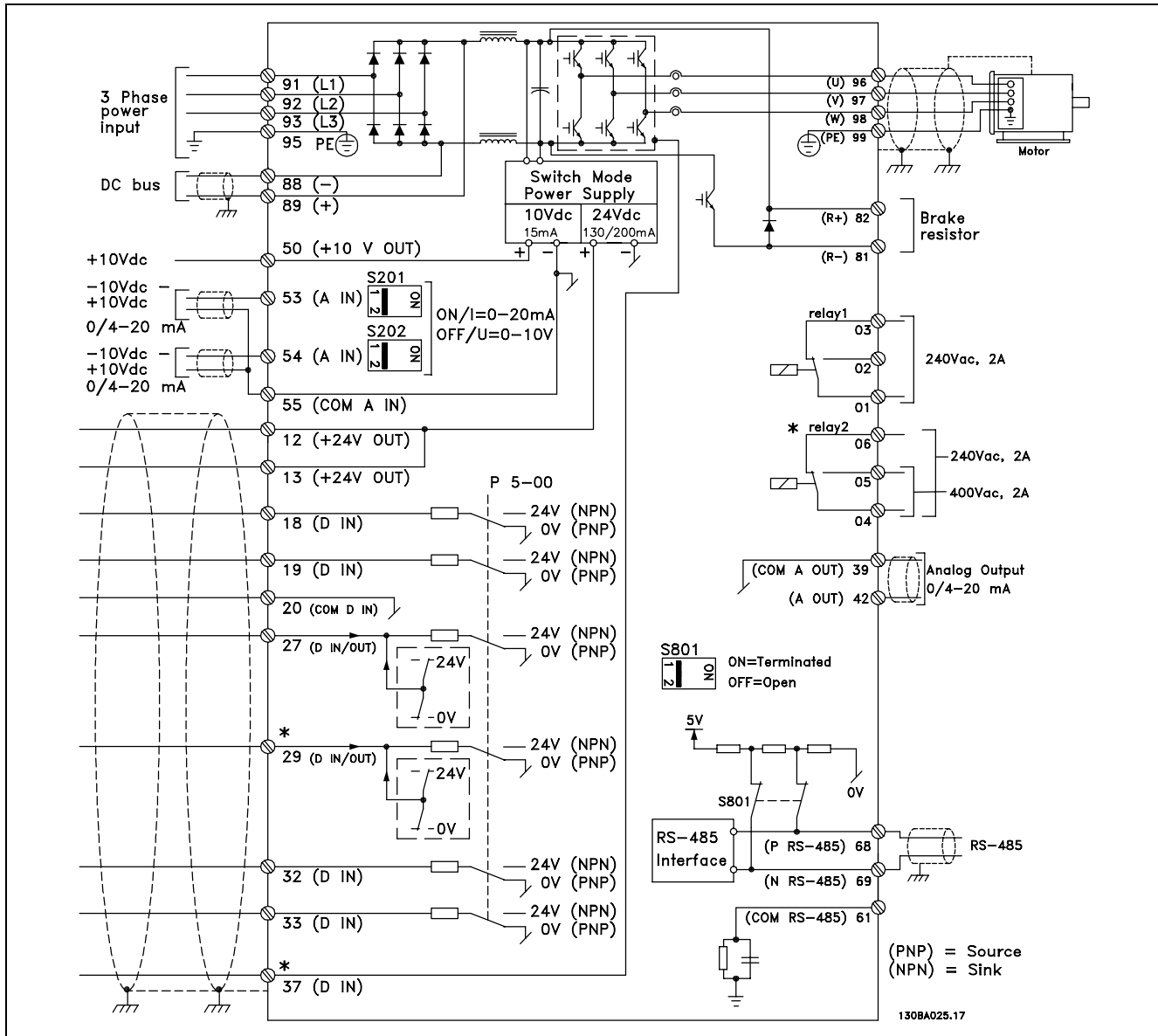
Diagram showing all electrical terminals without options.
Terminal 37 is the input to be used for Safe Stop. For instructions on Safe Stop installation please refer
to the section *Safe Stop Installation* in the FC 300 Design Guide.
* Terminal 37 is not included in FC 301 (Except FC 301 A1, which includes Safe Stop).
Terminal 29, Relay 2, is not included in FC 301.

Very long control cables and analog signals may in rare cases and depending on installation result
in 50/60 Hz earth loops due to noise from mains supply cables.

If this occurs, you may have to break the screen or insert a 100 nF capacitor between screen and chassis.

The digital and analog in- and outputs must be connected separately to the FC 300 common
inputs (terminal 20, 55, 39) to avoid ground currents from both groups to affect other groups. For
example, switching on the digital input may disturb the analog input signal.

— How to Install —

NB!:
Control cables must be screened/armoured.

1. Use a clamp from the accessory bag to connect the screen to the FC 300 decoupling plate for control cables.

See section entitled *Earthing of Screened/Armoured Control Cables* for the correct termination of control cables.

130BT305
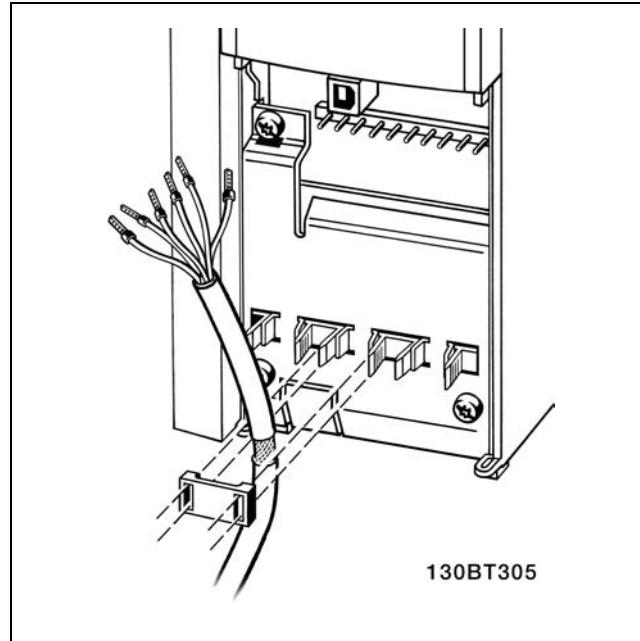
□ **Switches S201, S202, and S801**

Switches S201 (A53) and S202 (A54) are used to select a current (0-20 mA) or a voltage (-10 to 10 V) configuration of the analog input terminals 53 and 54 respectively.

Switch S801 (BUS TER.) can be used to enable termination on the RS-485 port (terminals 68 and 69).

See drawing *Diagram showing all electrical terminals* in section *Electrical Installation.*

Default setting:

    S201 (A53) = OFF (voltage input)
    S202 (A54) = OFF (voltage input)
    S801 (Bus termination) = OFF
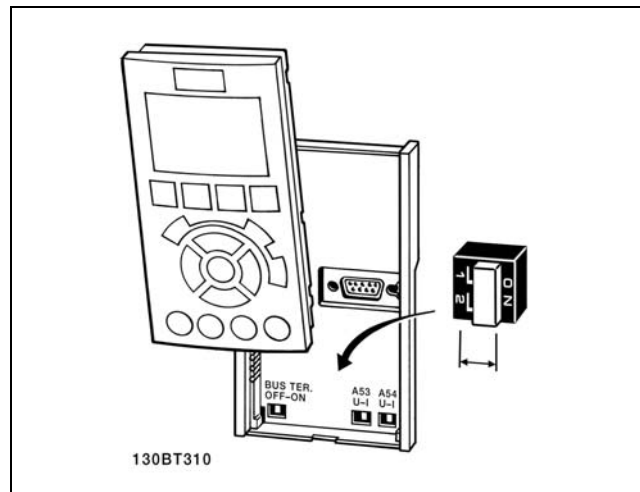
When changing the function of S201, S202 or S801 be careful not to use force for the switch over. It is recommended to remove the LCP fixture (cradle) when operating the switches. The switches must not be operated with power on the frequency converter.

130BT310

― How to Install ―

□ Final Set-Up and Test

To test the set-up and ensure that the frequency converter is running, follow these steps.

Step 1. Locate the motor name plate.

NB!:
The motor is either star- (Y) or delta-connected (Δ). This information is located on the motor name plate data.

BAUER D-73734 ESLINGEN				
3∼ MOTOR NR. 1827421		2003		
S/E005A9				
	1,5	kW		
n₂ 31,5 /min.		400	Y	V
n₁ 1400 /min.		50		Hz
cos φ 0,80		3,6		A
1,7L				
B	IP 65	H1/1A		

130BT307
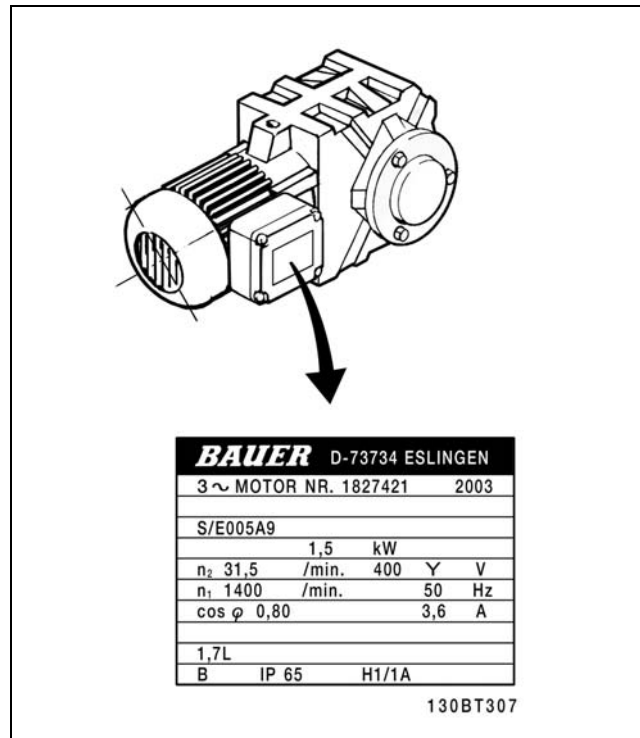
Step 2. Enter the motor name plate data in this parameter list.
To access this list first press the [QUICK MENU] key then select "Q2 Quick Setup".

Please refer to the chapter *How to programme*.

1.	Motor Power [kW]	par. 1-20
	or Motor Power [HP]	par. 1-21
2.	Motor Voltage	par. 1-22
3.	Motor Frequency	par. 1-23
4.	Motor Current	par. 1-24
5.	Motor Nominal Speed	par. 1-25

Step 3. Activate the Automatic Motor Adaptation (AMA)
Performing an AMA will ensure optimum performance. The AMA measures the values from the motor model equivalent diagram.

1. Connect terminal 37 to terminal 12 (FC 302).
2. Connect terminal 27 to terminal 12 or set par. 5-12 to 'No function' (par. 5-12 [0])
3. Activate the AMA par. 1-29.
4. Choose between complete or reduced AMA. If an LC filter is mounted, run only the reduced AMA, or remove the LC filter during the AMA procedure.
5. Press the [OK] key. The display shows "Press [Hand on] to start".
6. Press the [Hand on] key. A progress bar indicates if the AMA is in progress.

Stop the AMA during operation

1. Press the [OFF] key - the frequency converter enters into alarm mode and the display
   shows that the AMA was terminated by the user.

Successful AMA

1. The display shows "Press [OK] to finish AMA".
2. Press the [OK] key to exit the AMA state.

Unsuccessful AMA

1. The frequency converter enters into alarm mode. A description of the alarm can
   be found in the *Troubleshooting* section.
2. "Report Value" in the [Alarm Log] shows the last measuring sequence carried out by the
   AMA, before the frequency converter entered alarm mode. This number along with the
   description of the alarm will assist you in troubleshooting. If you contact Danfoss Service,
   make sure to mention number and alarm description.

NB!:
Unsuccessful AMA is often caused by incorrectly registered motor name plate data or too
big difference between the motor power size and the FC 300 power size.

Step 4. Set speed limit and ramp time

Set up the desired limits for speed and ramp time.

Minimum Reference	par. 3-02
Maximum Reference	par. 3-03

Motor Speed Low Limit	par. 4-11 or 4-12
Motor Speed High Limit	par. 4-13 or 4-14

Ramp-up Time 1 [s]	par. 3-41
Ramp-down Time 1 [s]	par. 3-42

□ **Additional Connections**

□ **Control of Mechanical Brake**
In hoisting/lowering applications, you need to be able to control an electro-mechanical brake.

- Control the brake using any relay output or digital output (terminal 27 or 29).
- Keep the output closed (voltage-free) as long as the frequency converter is unable to 'support' the motor, for example due to the load being too heavy.
- Select *Mechanical brake control* [32] in par. 5-4* for applications with an electro-mechanical brake.
- The brake is released when the motor current exceeds the preset value in par. 2-20.
- The brake is engaged when the output frequency is less than the frequency set in par. 2-21 or 2-22, and only if the frequency converter carries out a stop command.

If the frequency converter is in alarm mode or in an overvoltage situation, the mechanical immediately brake cuts in.

□ **Parallel Connection of Motors**
The FC 300 is able to control several parallel-connected motors. The total current consumption of the motors must not exceed the rated output current I_{INV} for the FC 300.
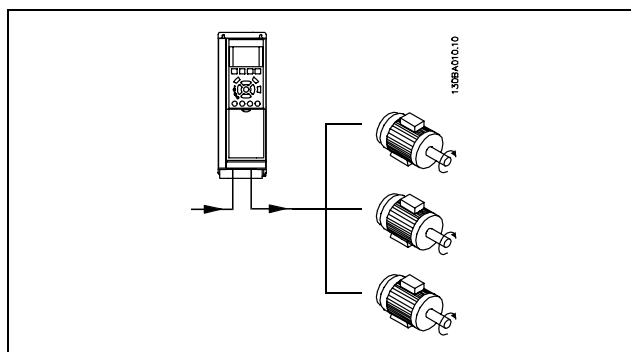
Problems may arise at start and at low RPM values if motor sizes are widely different because small motors' relatively high ohmic resistance in the stator calls for a higher voltage at start and at low RPM values.

The electronic thermal relay (ETR) of the FC 300 cannot be used as motor protection for the individual motor in systems with motors connected in parallel. Further motor protection must be provided, e.g. thermistors in each motor or individual thermal relays. (Circuit breakers are not suitable as protection).

NB!:
When motors are connected in parallel, parameter 1-29 *Automatic motor adaptation (AMA)* cannot be used.

For more information, see *VLT AutomationDrive FC 300 Design Guide.*

□ **Motor Thermal Protection**
The electronic thermal relay in FC 300 has received the UL-approval for single motor protection, when par. 1-90 *Motor Thermal Protection* is set for *ETR Trip* and par. 1-24 *Motor current, $I_{M,N}$* is set to the rated motor current (see motor name plate).

How to Programme
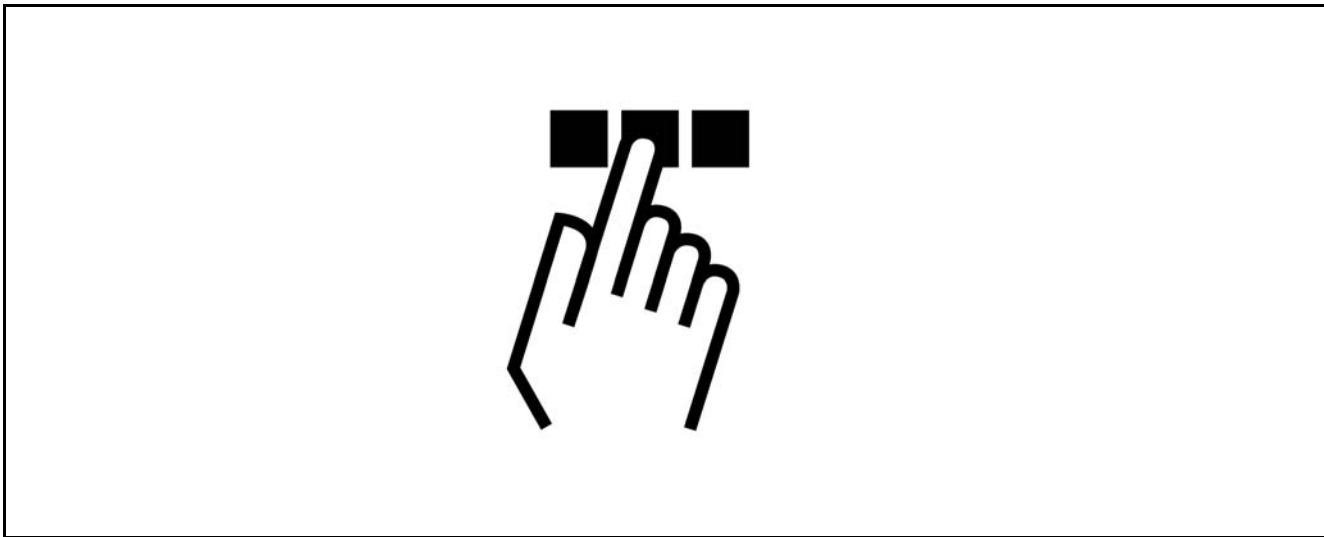
□ The FC 300 Graphical and Numerical LCP

The easiest programming of FC 300 frequency converters is performed by the Graphical Local Control Panel (G-LCP): It is necessary to consult FC 300 Design Guide when using Numeric Local Control Panel (N-LCP).

□ How to Programme on the Graphical Local Control Panel

The following instructions are valid for the graphical LCP (LCP 102):

The control panel is divided into four functional groups:
1. Graphical display with Status lines.
2. Menu keys and indicator lights - changing parameters and switching between display functions.
3. Navigation keys and indicator lights (LEDs).
4. Operation keys and indicator lights (LEDs).

All data is displayed in a graphical LCP display, which can show up to five items of operating data while displaying [Status].

Display lines:

a. **Status line:** Status messages displaying icons and graphic.
b. **Line 1-2:** Operator data lines displaying data defined or chosen by the user. By pressing the [Status] key, up to one extra line can be added.
c. **Status line:** Status messages displaying text.
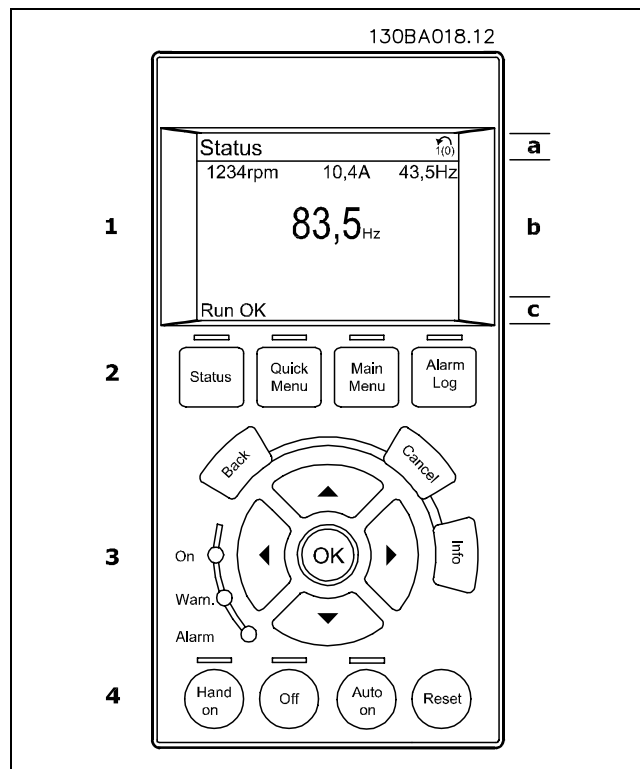
— How to Programme —

□ **How to Programme on the Numerical Local Control Panel**

The following instructions are valid for the numerical LCP (LCP 101):

The control panel is divided into four functional groups:

1. Numerical display.
2. Menu keys and indicator lights - changing parameters and switching between display functions.
3. Navigation keys and indicator lights (LEDs).
4. Operation keys and indicator lights (LEDs).

130BA191.10

□ **How to Programme on the Numerical Local Control Panel**
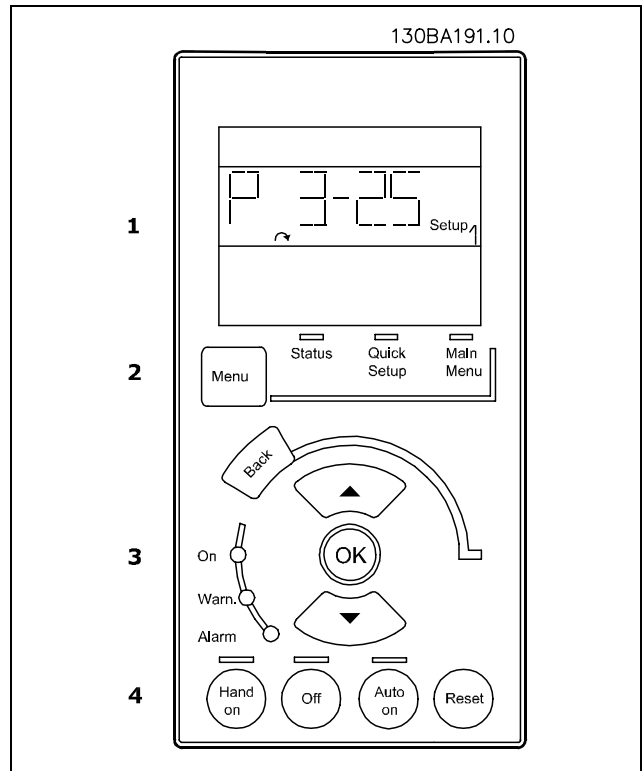
─ How to Programme ─

☐ Initial Commissioning

Doing the initial commissioning, the easiest way to go through is using the Quick Menu button and follows the quick set-up procedure using G-LCP:

Press

Quick Menu	↓	Q2 Quick Menu	OK	↓
0-01 Language	OK	Set language		↓
1-20 Motor power	OK	Set Motor nameplate power		↓
1-22 Motor voltage	OK	Set Nameplate voltage		↓
1-23 Motor frequency	OK	Set Nameplate frequency		↓
1-24 Motor current	OK	Set Nameplate current		↓
1-25 Motor nominal speed	OK	Set Nameplate speed in RPM		↓
5-12 Terminal 27 Digital Input	OK	If terminal default is *Coast inverse* it is possible to change this setting to *No function*. No connection to terminal 27 is then needed for running AMA		↓
1-29 Automatic Motor Adaptation	OK	Set desired AMA function. Enable complete AMA is recommended		↓
3-02 Minimum reference	OK	Set the minimum speed of the motor shaft		↓
3-03 Maximum reference	OK	Set the maximum speed of the motor shaft		↓
3-41 Ramp1 up time	OK	Set the ramping up time with reference to nominal motor speed (set in par. 1-25)		↓ ↓
3-43 Ramp1 down time	OK	Set the ramping down time with reference to nominal motor speed (set in par. 1-25)		↓
3-13 Reference site	OK	Set the site from where the reference must work		↓

— How to Programme —

□ Quick Setup

0-01 Language

Option:

✱ English (ENGLISH)	[0]
German (DEUTSCH)	[1]
French (FRANCAIS)	[2]
Danish (DANSK)	[3]
Spanish (ESPANOL)	[4]
Italian (ITALIANO)	[5]
Chinese (CHINESE)	[10]
Finnish (FINNISH)	[20]
English US (ENGLISH US)	[22]
Greek (GREEK)	[27]
Portuguese (PORTUGUESE)	[28]
Slovenian (SLOVENIAN)	[36]
Korean (KOREAN)	[39]
Japanese (JAPANESE)	[40]
Turkish (TURKISH)	[41]
Traditional Chinese	[42]
Bulgarian	[43]
Serbian	[44]
Romanian (ROMANIAN)	[45]
Hungarian (HUNGARIAN)	[46]
Czech	[47]
Polish (POLISH)	[48]
Russian	[49]
Thai	[50]
Bahasa Indonesian (BAHASA INDONESIAN)	[51]

Function:

Defines the language to be used in display.

The frequency converter can be delivered with 4 various language packages. English and German are included in all packages. English cannot be erased or manipulated.

Language package 1 consists of:
English, German, French, Danish, Spanish, Italian and Finnish.

Language package 2 consists of:
English, German, Chinese, Korean, Japanese, Thai and Bahasa Indonesian.

Language package 3 consists of:
English, German, Slovenian, Bulgarian, Serbian, Romanian, Hungarian, Czech and Russian.

Language package 4 consists of:
English, German, Spanish, English US, Greek, Brazilian Portuguese, Turkish and Polish.

1-20 Motor Power [kW]

Range:

Size dependent	[M-TYPE]

Function:

Enter the nominal motor power in kW according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit. This parameter cannot be adjusted while the motor is running.

1-22 Motor Voltage

Range:

200-600 V	[M-TYPE]

Function:

Enter the nominal motor voltage according to the motor nameplate data. The default value corresponds to the nominal rated output of the unit. This parameter cannot be adjusted while the motor is running.

1-23 Motor Frequency

Option:

✱ 50 Hz (50 HZ)	[50]
60 Hz (60 HZ)	[60]
Min - Max motor frequency: 20 - 300 Hz	

Function:

Select the motor frequency value from the motor nameplate data. Alternatively, set the value for motor frequency to be infinitely variable. If a value different from 50 Hz or 60 Hz is selected, it is necessary to adapt the load independent settings in par. 1-50 to 1-53. For 87 Hz operation with 230/400 V motors, set the nameplate data for 230 V/50 Hz. Adapt par. 4-13 *Motor Speed High Limit [RPM)* and par. 3-03 *Maximum Reference* to the 87 Hz application. This parameter cannot be adjusted while the motor is running.

1-24 Motor Current

Range:

Motor type dependent.	

Function:

Enter the nominal motor current value from the motor nameplate data. The data are used for calculating torque, motor protection etc. This parameter cannot be adjusted while the motor is running.

✱ default setting ( ) display text	[ ] value for use in communication via serial communication port

— How to Programme —

1-25 Motor Nominal Speed

Range:

100 - 60000 RPM   ✱ RPM

Function:

Enter the nominal motor speed value from the motor nameplate data. The data are used for calculating motor compensations. This parameter cannot be adjusted while the motor is running.

5-12 Terminal 27 Digital Input

Function:

Select the function from the available digital input range.

No operation	[0]
Reset	[1]
Coast inverse	[2]
Coast and reset inverse	[3]
Quick stop inverse	[4]
DC-brake inverse	[5]
Stop inverse	[6]
Start	[8]
Latched start	[9]
Reversing	[10]
Start reversing	[11]
Enable start forward	[12]
Enable start reverse	[13]
Jog	[14]
Preset ref bit 0	[16]
Preset ref bit 1	[17]
Preset ref bit 2	[18]
Freeze reference	[19]
Freeze output	[20]
Speed up	[21]
Speed down	[22]
Set-up select bit 0	[23]
Set-up select bit 1	[24]
Catch up	[28]
Slow down	[29]
Pulse input	[32]
Ramp bit 0	[34]
Ramp bit 1	[35]
Mains failure inverse	[36]
DigiPot Increase	[55]
DigiPot Decrease	[56]
DigiPot Clear	[57]
Reset Counter A	[62]
Reset Counter B	[65]

1-29 Automatic Motor Adaptation (AMA)

Option:

✱ OFF	[0]
Enable complete AMA	[1]
Enable reduced AMA	[2]

Function:

The AMA function optimises dynamic motor performance by automatically optimising the advanced motor parameters (par. 1-30 to par. 1-35) while the motor is stationary.

Select the type of AMA. _Enable complete AMA_ [1] performs AMA of the stator resistance R_S, the rotor resistance R_r, the stator leakage reactance x_1, the rotor leakage reactance X_2 and the main reactance X_h. Select this option if an LC filter is used between the drive and the motor.

FC 301: The Complete AMA does not include X_h measurement for FC 301. Instead, the X_h value is determined from the motor database. Par. 1-35 _Main Reactance (X_h)_ may be adjusted to obtain optimal start performance.

Select _Reduced AMA_ [2] performs a reduced AMA of the stator resistance R_s in the system only. Activate the AMA function by pressing [Hand on] after selecting [1] or [2]. See also the section _Automatic Motor Adaptation_. After a normal sequence, the display will read: "Press [OK] to finish AMA". After pressing the [OK] key the frequency converter is ready for operation.

Note:

- For the best adaptation of the frequency converter, run AMA on a cold motor.
- AMA cannot be performed while the motor is running.
- AMA cannot be performed on permanent magnet motors.

NB!:
It is important to set motor par. 1-2* Motor Data correctly, since these form part of the AMA algorithm. An AMA must be performed to achieve optimum dynamic motor performance. It may take up to 10 min, depending on the power rating of the motor.

NB!:
Avoid generating external torque during AMA.

NB!:
If one of the settings in par. 1-2* Motor Data is changed, par. 1-30 to 1-39, the advanced motor parameters, will return to default setting. This parameter cannot be adjusted while the motor is running.

3-02 Minimum Reference

Range:

-100000.000 - par. 3-03   ✱ 0.000 Unit

✱ default setting   ( ) display text   [ ] value for use in communication via serial communication port

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Function:

The *Minimum reference* is the minimum value obtained by the sum of all references. *Minimum reference* is only active if *Min - Max* [0] is set in par. 3-00.
Speed control, closed loop: RPM Torque control, speed feedback: Nm

3-03 Maximum Reference

Range:

Par. 3-02 - 100000.000   ✲1500.000 Unit

Function:

Enter the Maximum Reference. The Maximum Reference is the highest value obtainable by summing all references. The Maximum Reference unit matches
- the choice of configuration in par. 1-00 *Configuration Mode*: for *Speed closed loop* [1], RPM; for *Torque* [2], Nm.
- the unit selected in par. 3-01 *Reference/Feedback Unit*.

3-41 Ramp 1 Ramp up Time

Range:

0.01 - 3600.00 s   ✲ s

Function:

Enter the ramp-up time, i.e. the acceleration time from 0 RPM to the rated motor speed $n_{M,N}$ (par. 1-25). Choose a ramp-up time such that the output current does not exceed the current limit in par. 4-18 during ramping. The value 0.00 corresponds to 0.01 sec. in speed mode. See ramp-down time in par. 3-42.

$$Par. 3 - 41 = \frac{t_{acc} * n_{norm} \ [\ par. 1 - 25\ ]}{\triangle ref \ [RPM]} \ [s]$$

3-42 Ramp 1 Ramp Down Time

Range:

0.01 - 3600.00 s   ✲ s

Function:

Enter the ramp-down time, i.e. the deceleration time from the rated motor speed $n_{M,N}$ (par. 1-25) to 0 RPM. Choose a ramp-down time such that no over-voltage arises in the inverter due to regenerative operation of the motor, and such that the generated current does not exceed the current limit set in par. 4-18. The value 0.00 corresponds to 0.01 s in speed mode. See ramp-up time in par. 3-41.

$$Par. 3 - 42 = \frac{t_{acc} * n_{norm} \ [\ par. 1 - 25\ ]}{\triangle ref \ [RPM]} \ [s]$$
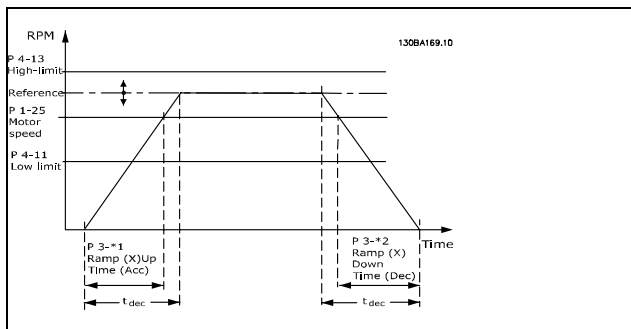
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Parameter Lists

Changes during operation
"TRUE" means that the parameter can be changed while the frequency converter is in operation and "FALSE" means that the it must be stopped before a change can be made.

4-Set-up
'All set-up': the parameters can be set individually in each of the four set-ups, i.e. one single parameter can have four different data values.
'1 set-up': data value will be the same in all set-ups.

Conversion index
This number refers to a conversion figure used when writing or reading by means of a frequency converter.

Conv. index	100	67	6	5	4	3	2	1	0	-1	-2	-3	-4	-5	-6
Conv. factor	1	1/60	1000000	100000	10000	1000	100	10	1	0.1	0.01	0.001	0.0001	0.00001	0.000001

Data type	Description	Type
2	Integer 8	Int8
3	Integer 16	Int16
4	Integer 32	Int32
5	Unsigned 8	Uint8
6	Unsigned 16	Uint16
7	Unsigned 32	Uint32
9	Visible String	VisStr
33	Normalized value 2 bytes	N2
35	Bit sequence of 16 boolean variables	V2
54	Time difference w/o date	TimD

See the *FC 300 Design Guide* for further information about data types 33, 35 and 54.

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Parameters for FC 300 are grouped into various parameter groups for easy selection of the correct parameters for optimized operation of the frequency converter.

1-xx Load and Motor parameters includes all load and motor related parameters

2-xx Brake parameters

3-xx References and ramping parameters includes DigiPot function

4-xx Limits Warnings; setting of limits and warning parameters

5-xx Digital inputs and outputs includes relay controls

6-xx Analog inputs and outputs

7-xx Controls; Setting parameters for speed and process controls

8-xx Communication and option parameters for setting of FC RS485 and FC USB port parameters.

9-xx Profibus parameters

10-xx DeviceNet and CAN Fieldbus parameters

13-xx Smart Logic Control parameters

14-xx Special function parameters

15-xx Drive information parameters

16-xx Read out parameters

17-xx Encoder Option parameters

32-xx MCO 305 Basic parameters

33-xx MCO 305 Advanced parameters

34-xx MCO Data Readout parameters

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□ **0-** **Operation/Display**

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
0-0*	**Basic Settings**						
0-01	Language	[0] English	1 set-up		TRUE	-	Uint8
0-02	Motor Speed Unit	[0] RPM	2 set-ups		FALSE	-	Uint8
0-03	Regional Settings	[0] International	2 set-ups		FALSE	-	Uint8
0-04	Operating State at Power-up (Hand)	[1] Forced stop, ref=old	All set-ups		TRUE	-	Uint8
0-1*	**Set-up Operations**						
0-10	Active Set-up	[1] Set-up 1	1 set-up		TRUE	-	Uint8
0-11	Edit Set-up	[1] Set-up 1	All set-ups		TRUE	-	Uint8
0-12	This Set-up Linked to	[0] Not linked	All set-ups		FALSE	-	Uint8
0-13	Readout: Linked Set-ups	0	All set-ups		FALSE	0	Uint16
0-14	Readout: Edit Set-ups / Channel	0	All set-ups		TRUE	0	Int32
0-2*	**LCP Display**						
0-20	Display Line 1.1 Small	Speed [RPM]	All set-ups		TRUE	-	Uint16
0-21	Display Line 1.2 Small	Motor current [A]	All set-ups		TRUE	-	Uint16
0-22	Display Line 1.3 Small	Power [kW]	All set-ups		TRUE	-	Uint16
0-23	Display Line 2 Large	Frequency [Hz]	All set-ups		TRUE	-	Uint16
0-24	Display Line 3 Large	Reference [%]	All set-ups		TRUE	-	Uint16
0-25	My Personal Menu	-	1 set-up		TRUE	0	Uint16
0-3*	**LCP Custom Readout**						
0-30	Unit for User-defined Readout	[0] None	All set-ups		TRUE	-	Uint8
0-31	Min Value of User-defined Readout	0.00	All set-ups		TRUE	-2	Int32
0-32	Max Value of User-defined Readout	100.00	All set-ups		TRUE	-2	Int32
0-4*	**LCP Keypad**						
0-40	[Hand on] Key on LCP	[1] Enabled	All set-ups		TRUE	-	Uint8
0-41	[Off] Key on LCP	[1] Enabled	All set-ups		TRUE	-	Uint8
0-42	[Auto on] Key on LCP	[1] Enabled	All set-ups		TRUE	-	Uint8
0-43	[Reset] Key on LCP	[1] Enabled	All set-ups		TRUE	-	Uint8
0-5*	**Copy/Save**						
0-50	LCP Copy	[0] No copy	All set-ups		FALSE	-	Uint8
0-51	Set-up Copy	[0] No copy	All set-ups		FALSE	-	Uint8
0-6*	**Password**						
0-60	Main Menu Password	100	1 set-up		TRUE	0	Uint16
0-61	Access to Main Menu w/o Password	[0] Full access	1 set-up		TRUE	-	Uint8
0-65	Quick Menu Password	200	1 set-up		TRUE	0	Uint16
0-66	Access to Quick Menu w/o Password	[0] Full access	1 set-up		TRUE	-	Uint8

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□ **1-** ** **Load/Motor**

Par. No. #	Parameter description	Default value (SR - Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
1-0*	**General Settings**						
1-00	Configuration Mode	-	All set-ups		TRUE	-	Uint8
1-01	Motor Control Principle	-	All set-ups		FALSE	-	Uint8
1-02	Flux Motor Feedback Source	[1] 24V encoder	All set-ups	x	FALSE	-	Uint8
1-03	Torque Characteristics	[0] Constant torque	All set-ups		TRUE	-	Uint8
1-04	Overload Mode	[0] High torque	All set-ups		FALSE	-	Uint8
1-05	Local Mode Configuration	[2] Mode as par 1-00	All set-ups		TRUE	-	Uint8
1-1*	**Motor Selection**						
1-10	Motor Construction	[0] Asynchron	All set-ups		FALSE	-	Uint8
1-2*	**Motor Data**						
1-20	Motor Power [kW]	SR	All set-ups		FALSE	1	Uint32
1-21	Motor Power [HP]	SR	All set-ups		FALSE	-2	Uint32
1-22	Motor Voltage	SR	All set-ups		FALSE	0	Uint16
1-23	Motor Frequency	SR	All set-ups		FALSE	0	Uint16
1-24	Motor Current	SR	All set-ups		FALSE	-2	Uint32
1-25	Motor Nominal Speed	SR	All set-ups		FALSE	67	Uint16
1-26	Motor Cont. Rated Torque	SR	All set-ups		FALSE	-1	Uint32
1-29	Automatic Motor Adaptation (AMA)	[0] Off	All set-ups		FALSE	-	Uint8
1-3*	**Adv. Motor Data**						
1-30	Stator Resistance (Rs)	SR	All set-ups		FALSE	-4	Uint32
1-31	Rotor Resistance (Rr)	SR	All set-ups		FALSE	-4	Uint32
1-33	Stator Leakage Reactance (X1)	SR	All set-ups		FALSE	-4	Uint32
1-34	Rotor Leakage Reactance (X2)	SR	All set-ups		FALSE	-4	Uint32
1-35	Main Reactance (Xh)	SR	All set-ups		FALSE	-4	Uint32
1-36	Iron Loss Resistance (Rfe)	SR	All set-ups		FALSE	-3	Uint32
1-37	d-axis Inductance (Ld)	SR	All set-ups	x	FALSE	-4	Int32
1-39	Motor Poles	SR	All set-ups		FALSE	0	Uint8
1-40	Back EMF at 1000 RPM	SR	All set-ups	x	FALSE	0	Uint16
1-41	Motor Angle Offset	0	All set-ups		FALSE	0	Int16
1-5*	**Load Indep. Setting**						
1-50	Motor Magnetisation at Zero Speed	100 %	All set-ups		TRUE	0	Uint16
1-51	Min Speed Normal Magnetising [RPM]	SR	All set-ups		TRUE	67	Uint16
1-52	Min Speed Normal Magnetising [Hz]	SR	All set-ups		TRUE	-1	Uint16
1-53	Model Shift Frequency	SR	All set-ups	x	FALSE	-1	Uint16
1-55	U/f Characteristic - U	SR	All set-ups		TRUE	-1	Uint16
1-56	U/f Characteristic - F	SR	All set-ups		TRUE	-1	Uint16
1-6*	**Load Depen. Setting**						
1-60	Low Speed Load Compensation	100 %	All set-ups		TRUE	0	Int16
1-61	High Speed Load Compensation	100 %	All set-ups		TRUE	0	Int16
1-62	Slip Compensation	SR	All set-ups		TRUE	0	Int16
1-63	Slip Compensation Time Constant	0.10 s	All set-ups		TRUE	-2	Uint16
1-64	Resonance Dampening	100 %	All set-ups		TRUE	0	Uint16
1-65	Resonance Dampening Time Constant	5 ms	All set-ups		TRUE	-3	Uint8
1-66	Min. Current at Low Speed	100 %	All set-ups	x	TRUE	0	Uint8
1-67	Load Type	[0] Passive load	All set-ups	x	TRUE	-	Uint8
1-68	Minimum Inertia	SR	All set-ups	x	FALSE	-4	Uint32
1-69	Maximum Inertia	SR	All set-ups	x	FALSE	-4	Uint32

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Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
1-7*	**Start Adjustments**						
1-71	Start Delay	0.0 s	All set-ups		TRUE	-1	Uint8
1-72	Start Function	[2] Coast/delay time	All set-ups		TRUE	-	Uint8
1-73	Flying Start [RPM]	[0] Disabled	All set-ups		FALSE	-	Uint8
1-74	Start Speed [RPM]	SR	All set-ups		TRUE	67	Uint16
1-75	Start Speed [Hz]	SR	All set-ups		TRUE	-1	Uint16
1-76	Start Current	0.00 A	All set-ups		TRUE	-2	Uint32
1-8*	**Stop Adjustments**						
1-80	Function at Stop	[0] Coast	All set-ups		TRUE	-	Uint8
1-81	Min Speed for Function at Stop [RPM]	SR	All set-ups		TRUE	67	Uint16
1-82	Min Speed for Function at Stop [Hz]	SR	All set-ups		TRUE	-1	Uint16
1-83	Precise Stop Function	[0] Precise ramp stop	All set-ups		FALSE	-	Uint8
1-84	Precise Stop Counter Value	100000	All set-ups		TRUE	0	Uint32
1-85	Precise Stop Speed Compensation Delay	10 ms	All set-ups		TRUE	-3	Uint8
1-9*	**Motor Temperature**						
1-90	Motor Thermal Protection	[0] No protection	All set-ups		TRUE	-	Uint8
1-91	Motor External Fan	[0] No	All set-ups		TRUE	-	Uint16
1-93	Thermistor Resource	[0] None	All set-ups		TRUE	-	Uint8
1-95	KTY Sensor Type	[0] KTY Sensor 1	All set-ups	x	TRUE	-	Uint8
1-96	KTY Thermistor Resource	[0] None	All set-ups	x	TRUE	-	Uint8
1-97	KTY Threshold level	80 °C	1 set-up	x	TRUE	100	Int16

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□ **2-** **Brakes**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
2-0*	**DC-Brake**						
2-00	DC Hold Current	50 %	All set-ups		TRUE	0	Uint8
2-01	DC Brake Current	50 %	All set-ups		TRUE	0	Uint16
2-02	DC Braking Time	10.0 s	All set-ups		TRUE	-1	Uint16
2-03	DC Brake Cut In Speed [RPM]	SR	All set-ups		TRUE	67	Uint16
2-04	DC Brake Cut In Speed [Hz]	SR	All set-ups		TRUE	-1	Uint16
2-1*	**Brake Energy Funct.**						
2-10	Brake Function	-	All set-ups		TRUE	-	Uint8
2-11	Brake Resistor (ohm)	SR	All set-ups		TRUE	0	Uint16
2-12	Brake Power Limit (kW)	SR	All set-ups		TRUE	0	Uint32
2-13	Brake Power Monitoring	[0] Off	All set-ups		TRUE	-	Uint8
2-15	Brake Check	[0] Off	All set-ups		TRUE	-	Uint8
2-16	AC brake Max. Current	100.0 %	All set-ups		TRUE	-1	Uint32
2-17	Over-voltage Control	[0] Disabled	All set-ups		TRUE	-	Uint8
2-2*	**Mechanical Brake**						
2-20	Release Brake Current	SR	All set-ups		TRUE	-2	Uint32
2-21	Activate Brake Speed [RPM]	SR	All set-ups		TRUE	67	Uint16
2-22	Activate Brake Speed [Hz]	SR	All set-ups		TRUE	-1	Uint16
2-23	Activate Brake Delay	0.0 s	All set-ups		TRUE	-1	Uint8

□ **2-** **Brakes**

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□ 3-** Reference / Ramps

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
3-0*	**Reference Limits**						
3-00	Reference Range	-	All set-ups		TRUE	-	Uint8
3-01	Reference/Feedback Unit	-	All set-ups		TRUE	-	Uint8
3-02	Minimum Reference	SR	All set-ups		TRUE	-3	Int32
3-03	Maximum Reference	SR	All set-ups		TRUE	-3	Int32
3-04	Reference Function	[0] Sum	All set-ups		TRUE	-	Uint8
3-1*	**References**						
3-10	Preset Reference	0.00 %	All set-ups		TRUE	-2	Int16
3-11	Jog Speed [Hz]	SR	All set-ups		TRUE	-1	Uint16
3-12	Catch up/slow Down Value	0.00 %	All set-ups		TRUE	-2	Int16
3-13	Reference Site	[0] Linked to Hand / Auto	All set-ups		TRUE	-	Uint8
3-14	Preset Relative Reference	0.00 %	All set-ups		TRUE	-2	Int32
3-15	Reference Resource 1	-	All set-ups		TRUE	-	Uint8
3-16	Reference Resource 2	-	All set-ups		TRUE	-	Uint8
3-17	Reference Resource 3	-	All set-ups		TRUE	-	Uint8
3-18	Relative Scaling Reference Resource	[0] No function	All set-ups		TRUE	-	Uint8
3-19	Jog Speed [RPM]	SR	All set-ups		TRUE	67	Uint16
3-4*	**Ramp 1**						
3-40	Ramp 1 Type	[0] Linear	All set-ups		TRUE	-	Uint8
3-41	Ramp 1 Ramp up Time	SR	All set-ups		TRUE	-2	Uint32
3-42	Ramp 1 Ramp Down Time	SR	All set-ups		TRUE	-2	Uint32
3-45	Ramp 1 S-ramp Ratio at Accel. Start	50 %	All set-ups		TRUE	0	Uint8
3-46	Ramp 1 S-ramp Ratio at Accel. End	50 %	All set-ups		TRUE	0	Uint8
3-47	Ramp 1 S-ramp Ratio at Decel. Start	50 %	All set-ups		TRUE	0	Uint8
3-48	Ramp 1 S-ramp Ratio at Decel. End	50 %	All set-ups		TRUE	0	Uint8
3-5*	**Ramp 2**						
3-50	Ramp 2 Type	[0] Linear	All set-ups		TRUE	-	Uint8
3-51	Ramp 2 Ramp up Time	SR	All set-ups		TRUE	-2	Uint32
3-52	Ramp 2 Ramp down Time	SR	All set-ups		TRUE	-2	Uint32
3-55	Ramp 2 S-ramp Ratio at Accel. Start	50 %	All set-ups		TRUE	0	Uint8
3-56	Ramp 2 S-ramp Ratio at Accel. End	50 %	All set-ups		TRUE	0	Uint8
3-57	Ramp 2 S-ramp Ratio at Decel. Start	50 %	All set-ups		TRUE	0	Uint8
3-58	Ramp 2 S-ramp Ratio at Decel. End	50 %	All set-ups		TRUE	0	Uint8
3-6*	**Ramp 3**						
3-60	Ramp 3 Type	[0] Linear	All set-ups		TRUE	-	Uint8
3-61	Ramp 3 Ramp up Time	SR	All set-ups		TRUE	-2	Uint32
3-62	Ramp 3 Ramp down Time	SR	All set-ups		TRUE	-2	Uint32
3-65	Ramp 3 S-ramp Ratio at Accel. Start	50 %	All set-ups		TRUE	0	Uint8
3-66	Ramp 3 S-ramp Ratio at Accel. End	50 %	All set-ups		TRUE	0	Uint8
3-67	Ramp 3 S-ramp Ratio at Decel. Start	50 %	All set-ups		TRUE	0	Uint8
3-68	Ramp 3 S-ramp Ratio at Decel. End	50 %	All set-ups		TRUE	0	Uint8

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Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conversion index	Type
3-7*	**Ramp 4**						
3-70	Ramp 4 Type	[0] Linear	All set-ups		TRUE	-	Uint8
3-71	Ramp 4 Ramp up Time	SR	All set-ups		TRUE	-2	Uint32
3-72	Ramp 4 Ramp Down Time	SR	All set-ups		TRUE	-2	Uint32
3-75	Ramp 4 S-ramp Ratio at Accel. Start	50 %	All set-ups		TRUE	0	Uint8
3-76	Ramp 4 S-ramp Ratio at Accel. End	50 %	All set-ups		TRUE	0	Uint8
3-77	Ramp 4 S-ramp Ratio at Decel. Start	50 %	All set-ups		TRUE	0	Uint8
3-78	Ramp 4 S-ramp Ratio at Decel. End	50 %	All set-ups		TRUE	0	Uint8
3-8*	**Other Ramps**						
3-80	Jog Ramp Time	SR	All set-ups		TRUE	-2	Uint32
3-81	Quick Stop Ramp Time	SR	2 set-ups		TRUE	-2	Uint32
3-9*	**Digital Pot.Meter**						
3-90	Step Size	0.10 %	All set-ups		TRUE	-2	Uint16
3-91	Ramp Time	1.00 s	All set-ups		TRUE	-2	Uint32
3-92	Power Restore	[0] Off	All set-ups		TRUE	-	Uint8
3-93	Maximum Limit	100 %	All set-ups		TRUE	0	Int16
3-94	Minimum Limit	-100 %	All set-ups		TRUE	0	Int16
3-95	Ramp Delay	1.000 N/A	All set-ups		TRUE	-3	TimD

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□ **4-** *** Limits / Warnings**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conversion index	Type
4-1*	**Motor Limits**						
4-10	Motor Speed Direction	-	All set-ups		FALSE	-	Uint8
4-11	Motor Speed Low Limit [RPM]	SR	All set-ups		TRUE	67	Uint16
4-12	Motor Speed Low Limit [Hz]	SR	All set-ups		TRUE	-1	Uint16
4-13	Motor Speed High Limit [RPM]	SR	All set-ups		TRUE	67	Uint16
4-14	Motor Speed High Limit [Hz]	SR	All set-ups		TRUE	-1	Uint16
4-16	Torque Limit Motor Mode	160.0 %	All set-ups		TRUE	-1	Uint16
4-17	Torque Limit Generator Mode	100.0 %	All set-ups		TRUE	-1	Uint16
4-18	Current Limit	ExpressionLimitSR	All set-ups		TRUE	-1	Uint32
4-19	Max Output Frequency	132.0 Hz	All set-ups		FALSE	-1	Uint16
4-2*	**Limit Factors**						
4-20	Torque Limit Factor Source	[0] No function	All set-ups		TRUE	-	Uint8
4-21	Speed Limit Factor Source	[0] No function	All set-ups		TRUE	-	Uint8
4-3*	**Motor Fb Monitor**						
4-30	Motor Feedback Loss Function	[2] Trip	All set-ups		TRUE	-	Uint8
4-31	Motor Feedback Speed Error	300 RPM	All set-ups		TRUE	67	Uint16
4-32	Motor Feedback Loss Timeout	0.05 s	All set-ups		TRUE	-2	Uint16
4-5*	**Adj. Warnings**						
4-50	Warning Current Low	0.00 A	All set-ups		TRUE	-2	Uint32
4-51	Warning Current High	ImaxVLT	All set-ups		TRUE	-2	Uint32
4-52	Warning Speed Low	0 RPM	All set-ups		TRUE	67	Uint16
4-53	Warning Speed High	(P413)	All set-ups		TRUE	67	Uint16
4-54	Warning Reference Low	-999999.999	All set-ups		TRUE	-3	Int32
4-55	Warning Reference High	999999.999	All set-ups		TRUE	-3	Int32
4-56	Warning Feedback Low	-999999.999	All set-ups		TRUE	-3	Int32
4-57	Warning Feedback High	999999.999	All set-ups		TRUE	-3	Int32
4-58	Missing Motor Phase Function	[1] On	All set-ups		TRUE	-	Uint8
4-6*	**Speed Bypass**						
4-60	Bypass Speed From [RPM]	SR	All set-ups		TRUE	67	Uint16
4-61	Bypass Speed From [Hz]	SR	All set-ups		TRUE	-1	Uint16
4-62	Bypass Speed To [RPM]	SR	All set-ups		TRUE	67	Uint16
4-63	Bypass Speed To [Hz]	SR	All set-ups		TRUE	-1	Uint16

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□ **5-** ** ** Digital In/Out**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conversion index	Type
5-0* Digital I/O mode							
5-00	Digital I/O Mode	[0] PNP	All set-ups		FALSE	-	Uint8
5-01	Terminal 27 Mode	[0] Input	All set-ups		TRUE	-	Uint8
5-02	Terminal 29 Mode	[0] Input	All set-ups	x	TRUE	-	Uint8
5-1* Digital Inputs							
5-10	Terminal 18 Digital Input	-	All set-ups		TRUE	-	Uint8
5-11	Terminal 19 Digital Input	-	All set-ups		TRUE	-	Uint8
5-12	Terminal 27 Digital Input	-	All set-ups		TRUE	-	Uint8
5-13	Terminal 29 Digital Input	-	All set-ups	x	TRUE	-	Uint8
5-14	Terminal 32 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-15	Terminal 33 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-16	Terminal X30/2 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-17	Terminal X30/3 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-18	Terminal X30/4 Digital Input	[0] No operation	All set-ups		TRUE	-	Uint8
5-3* Digital Outputs							
5-30	Terminal 27 Digital Output	-	All set-ups		TRUE	-	Uint8
5-31	Terminal 29 Digital Output	-	All set-ups	x	TRUE	-	Uint8
5-32	Term X30/6 Digi Out (MCB 101)	-	All set-ups		TRUE	-	Uint8
5-33	Term X30/7 Digi Out (MCB 101)	-	All set-ups		TRUE	-	Uint8
5-4* Relays							
5-40	Function Relay	-	All set-ups		TRUE	-	Uint8
5-41	On Delay, Relay	0.01 s	All set-ups		TRUE	-2	Uint16
5-42	Off Delay, Relay	0.01 s	All set-ups		TRUE	-2	Uint16
5-5* Pulse Input							
5-50	Term. 29 Low Frequency	100 Hz	All set-ups	x	TRUE	0	Uint32
5-51	Term. 29 High Frequency	100 Hz	All set-ups	x	TRUE	0	Uint32
5-52	Term. 29 Low Ref./Feedb. Value	0.000	All set-ups	x	TRUE	-3	Int32
5-53	Term. 29 High Ref./Feedb. Value	SR	All set-ups	x	TRUE	-3	Int32
5-54	Pulse Filter Time Constant #29	100 ms	All set-ups	x	FALSE	-3	Uint16
5-55	Term. 33 Low Frequency	100 Hz	All set-ups		TRUE	0	Uint32
5-56	Term. 33 High Frequency	100 Hz	All set-ups		TRUE	0	Uint32
5-57	Term. 33 Low Ref./Feedb. Value	0.000	All set-ups		TRUE	-3	Int32
5-58	Term. 33 High Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
5-59	Pulse Filter Time Constant #33	100 ms	All set-ups		FALSE	-3	Uint16
5-6* Pulse Output							
5-60	Terminal 27 Pulse Output Variable	-	All set-ups		TRUE	-	Uint8
5-62	Pulse Output Max Freq #27	SR	All set-ups		TRUE	0	Uint32
5-63	Terminal 29 Pulse Output Variable	-	All set-ups	x	TRUE	-	Uint8
5-65	Pulse Output Max Freq #29	SR	All set-ups	x	TRUE	0	Uint32
5-66	Terminal X30/6 Pulse Output Variable	-	All set-ups		TRUE	-	Uint8
5-68	Pulse Output Max Freq #X30/6	SR	All set-ups		TRUE	0	Uint32

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Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
5-7* 24V Encoder Input							
5-70	Term 32/33 Pulses per Revolution	1024	All set-ups		FALSE	0	Uint16
5-71	Term 32/33 Encoder Direction	[0] Clockwise	All set-ups		FALSE	-	Uint8
5-9* Bus Controlled							
5-90	Digital & Relay Bus Control	0	All set-ups		TRUE	0	Uint32
5-93	Pulse Out #27 Bus Control	0.00 %	All set-ups		TRUE	-2	N2
5-94	Pulse Out #27 Timeout Preset	0.00 %	1 set-up		TRUE	-2	Uint16
5-95	Pulse Out #29 Bus Control	0.00 %	All set-ups	x	TRUE	-2	N2
5-96	Pulse Out #29 Timeout Preset	0.00 %	1 set-up	x	TRUE	-2	Uint16

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□ 6-** Analog In/Out

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
6-0* Analog I/O Mode							
6-00	Live Zero Timeout Time	10 s	All set-ups		TRUE	0	Uint8
6-01	Live Zero Timeout Function	[0] Off	All set-ups		TRUE	-	Uint8
6-1* Analog Input 1							
6-10	Terminal 53 Low Voltage	0.07 V	All set-ups		TRUE	-2	Int16
6-11	Terminal 53 High Voltage	10.00 V	All set-ups		TRUE	-2	Int16
6-12	Terminal 53 Low Current	0.14 mA	All set-ups		TRUE	-5	Int16
6-13	Terminal 53 High Current	20.00 mA	All set-ups		TRUE	-5	Int16
6-14	Terminal 53 Low Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-15	Terminal 53 High Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-16	Terminal 53 Filter Time Constant	0.001 s	All set-ups		TRUE	-3	Uint16
6-2* Analog Input 2							
6-20	Terminal 54 Low Voltage	0.07 V	All set-ups		TRUE	-2	Int16
6-21	Terminal 54 High Voltage	10.00 V	All set-ups		TRUE	-2	Int16
6-22	Terminal 54 Low Current	0.14 mA	All set-ups		TRUE	-5	Int16
6-23	Terminal 54 High Current	20.00 mA	All set-ups		TRUE	-5	Int16
6-24	Terminal 54 Low Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-25	Terminal 54 High Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-26	Terminal 54 Filter Time Constant	0.001 s	All set-ups		TRUE	-3	Uint16
6-3* Analog Input 3							
6-30	Terminal X30/11 Low Voltage	0.07 V	All set-ups		TRUE	-2	Int16
6-31	Terminal X30/11 High Voltage	10.00 V	All set-ups		TRUE	-2	Int16
6-34	Term. X30/11 Low Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-35	Term. X30/11 High Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-36	Term. X30/11 Filter Time Constant	0.001 s	All set-ups		TRUE	-3	Uint16
6-4* Analog Input 4							
6-40	Terminal X30/12 Low Voltage	0.07 V	All set-ups		TRUE	-2	Int16
6-41	Terminal X30/12 High Voltage	10.00 V	All set-ups		TRUE	-2	Int16
6-44	Term. X30/12 Low Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-45	Term. X30/12 High Ref./Feedb. Value	SR	All set-ups		TRUE	-3	Int32
6-46	Term. X30/12 Filter Time Constant	0.001 s	All set-ups		TRUE	-3	Uint16
6-5* Analog Output 1							
6-50	Terminal 42 Output	-	All set-ups		TRUE	-	Uint8
6-51	Terminal 42 Output Min Scale	0.00 %	All set-ups		TRUE	-2	Int16
6-52	Terminal 42 Output Max Scale	100.00 %	All set-ups		TRUE	-2	Int16
6-53	Terminal 42 Output Bus Control	0.00 %	All set-ups		TRUE	-2	N2
6-54	Terminal 42 Output Timeout Preset	0.00 %	1 set-up		TRUE	-2	Uint16
6-6* Analog Output 2							
6-60	Terminal X30/8 Output	-	All set-ups		TRUE	-	Uint8
6-61	Terminal X30/8 Min. Scale	0.00 %	All set-ups		TRUE	-2	Int16
6-62	Terminal X30/8 Max. Scale	100.00 %	All set-ups		TRUE	-2	Int16

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□ **7-** Controllers**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
7-0*	**Speed PID Ctrl.**						
7-00	Speed PID Feedback Source	-	All set-ups		FALSE	-	Uint8
7-02	Speed PID Proportional Gain	SR	All set-ups		TRUE	-3	Uint16
7-03	Speed PID Integral Time	SR	All set-ups		TRUE	-4	Uint32
7-04	Speed PID Differentiation Time	SR	All set-ups		TRUE	-4	Uint16
7-05	Speed PID Diff. Gain Limit	5.0 N/A	All set-ups		TRUE	-1	Uint16
7-06	Speed PID Lowpass Filter Time	10.0 ms	All set-ups		TRUE	-4	Uint16
7-08	Speed PID Feed Forward Factor	0 %	All set-ups		FALSE	0	Uint16
7-2*	**Process Ctrl. Feedb**						
7-20	Process CL Feedback 1 Resource	[0] No function	All set-ups		TRUE	-	Uint8
7-22	Process CL Feedback 2 Resource	[0] No function	All set-ups		TRUE	-	Uint8
7-3*	**Process PID Ctrl.**						
7-30	Process PID Normal/ Inverse Control	[0] Normal	All set-ups		TRUE	-	Uint8
7-31	Process PID Anti Windup	[1] On	All set-ups		TRUE	-	Uint8
7-32	Process PID Start Speed	0 RPM	All set-ups		TRUE	67	Uint16
7-33	Process PID Proportional Gain	0.01	All set-ups		TRUE	-2	Uint16
7-34	Process PID Integral Time	10000.00 s	All set-ups		TRUE	-2	Uint32
7-35	Process PID Differentiation Time	0.00 s	All set-ups		TRUE	-2	Uint16
7-36	Process PID Diff. Gain Limit	5.0	All set-ups		TRUE	-1	Uint16
7-38	Process PID Feed Forward Factor	0 %	All set-ups		TRUE	0	Uint16
7-39	On Reference Bandwidth	5 %	All set-ups		TRUE	0	Uint8

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□ **8-** * **Comm. and Options**

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
8-0*	**General Settings**						
8-01	Control Site	[0] Digital and ctrl.word	All set-ups		TRUE	-	Uint8
8-02	Control Word Source	-	All set-ups		TRUE	-	Uint8
8-03	Control Word Timeout Time	1.0 s	1 set-up		TRUE	-1	Uint32
8-04	Control Word Timeout Function	[0] Off	1 set-up		TRUE	-	Uint8
8-05	End-of-Timeout Function	[1] Resume set-up	1 set-up		TRUE	-	Uint8
8-06	Reset Control Word Timeout	[0] Do not reset	All set-ups		TRUE	-	Uint8
8-07	Diagnosis Trigger	[0] Disable	2 set-ups		TRUE	-	Uint8
8-1*	**Ctrl. Word Settings**						
8-10	Control Word Profile	[0] FC profile	All set-ups		TRUE	-	Uint8
8-13	Configurable Status Word STW	[1] Profile Default	All set-ups		TRUE	-	Uint8
8-3*	**FC Port Settings**						
8-30	Protocol	[0] FC	1 set-up		TRUE	-	Uint8
8-31	Address	1	1 set-up		TRUE	0	Uint8
8-32	FC Port Baud Rate	[2] 9600 Baud	1 set-up		TRUE	-	Uint8
8-35	Minimum Response Delay	10 ms	All set-ups		TRUE	-3	Uint16
8-36	Max Response Delay	5000 ms	1 set-up		TRUE	-3	Uint16
8-37	Max Inter-Char Delay	25 ms	1 set-up		TRUE	-3	Uint16
8-4*	**FC MC protocol set**						
8-40	Telegram selection	[1] Standard telegram 1	2 set-ups		TRUE	-	Uint8
8-5*	**Digital/Bus**						
8-50	Coasting Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-51	Quick Stop Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-52	DC Brake Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-53	Start Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-54	Reversing Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-55	Set-up Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-56	Preset Reference Select	[3] Logic OR	All set-ups		TRUE	-	Uint8
8-9*	**Bus Jog**						
8-90	Bus Jog 1 Speed	100 RPM	All set-ups		TRUE	67	Uint16
8-91	Bus Jog 2 Speed	200 RPM	All set-ups		TRUE	67	Uint16

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□ **9-** Profibus**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
9-00	Setpoint	0	All set-ups		TRUE	0	Uint16
9-07	Actual Value	0	All set-ups		FALSE	0	Uint16
9-15	PCD Write Configuration	SR	2 set-ups		TRUE	-	Uint16
9-16	PCD Read Configuration	SR	2 set-ups		TRUE	-	Uint16
9-18	Node Address	126	1 set-up		TRUE	0	Uint8
9-22	Telegram Selection	[108] PPO 8	1 set-up		TRUE	-	Uint8
9-23	Parameters for Signals	0	All set-ups		TRUE	-	Uint16
9-27	Parameter Edit	[1] Enabled	2 set-ups		FALSE	-	Uint16
9-28	Process Control	[1] Enable cyclic master	2 set-ups		FALSE	-	Uint8
9-44	Fault Message Counter	0	All set-ups		TRUE	0	Uint16
9-45	Fault Code	0	All set-ups		TRUE	0	Uint16
9-47	Fault Number	0	All set-ups		TRUE	0	Uint16
9-52	Fault Situation Counter	0	All set-ups		TRUE	0	Uint16
9-53	Profibus Warning Word	0	All set-ups		TRUE	0	V2
9-63	Actual Baud Rate	[255] No baudrate found	All set-ups		TRUE	-	Uint8
9-64	Device Identification	0	All set-ups		TRUE	0	Uint16
9-65	Profile Number	0	All set-ups		TRUE	0	Oct-Str[2]
9-67	Control Word 1	0	All set-ups		TRUE	0	V2
9-68	Status Word 1	0	All set-ups		TRUE	0	V2
9-71	Profibus Save Data Values	[0] Off	All set-ups		TRUE	-	Uint8
9-72	ProfibusDriveReset	[0] No action	1 set-up		FALSE	-	Uint8
9-80	Defined Parameters (1)	0	All set-ups		FALSE	0	Uint16
9-81	Defined Parameters (2)	0	All set-ups		FALSE	0	Uint16
9-82	Defined Parameters (3)	0	All set-ups		FALSE	0	Uint16
9-83	Defined Parameters (4)	0	All set-ups		FALSE	0	Uint16
9-84	Defined Parameters (5)	0	All set-ups		FALSE	0	Uint16
9-90	Changed Parameters (1)	0	All set-ups		FALSE	0	Uint16
9-91	Changed Parameters (2)	0	All set-ups		FALSE	0	Uint16
9-92	Changed Parameters (3)	0	All set-ups		FALSE	0	Uint16
9-93	Changed parameters (4)	0	All set-ups		FALSE	0	Uint16
9-94	Changed parameters (5)	0	All set-ups		FALSE	0	Uint16

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□ 10-** CAN Fieldbus

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conversion index	Type
10-0* Common Settings							
10-00	CAN Protocol	-	2 set-ups		FALSE	-	Uint8
10-01	Baud Rate Select	-	2 set-ups		TRUE	-	Uint8
10-02	MAC ID	SR	2 set-ups		TRUE	0	Uint8
10-05	Readout Transmit Error Counter	0	All set-ups		TRUE	0	Uint8
10-06	Readout Receive Error Counter	0	All set-ups		TRUE	0	Uint8
10-07	Readout Bus Off Counter	0	All set-ups		TRUE	0	Uint8
10-1* DeviceNet							
10-10	Process Data Type Selection	-	All set-ups		TRUE	-	Uint8
10-11	Process Data Config Write	SR	2 set-ups		TRUE	-	Uint16
10-12	Process Data Config Read	SR	2 set-ups		TRUE	-	Uint16
10-13	Warning Parameter	0	All set-ups		TRUE	0	Uint16
10-14	Net Reference	[0] Off	2 set-ups		TRUE	-	Uint8
10-15	Net Control	[0] Off	2 set-ups		TRUE	-	Uint8
10-2* COS Filters							
10-20	COS Filter 1	0	All set-ups		FALSE	0	Uint16
10-21	COS Filter 2	0	All set-ups		FALSE	0	Uint16
10-22	COS Filter 3	0	All set-ups		FALSE	0	Uint16
10-23	COS Filter 4	0	All set-ups		FALSE	0	Uint16
10-3* Parameter Access							
10-30	Array Index	0	2 set-ups		TRUE	0	Uint8
10-31	Store Data Values	[0] Off	All set-ups		TRUE	-	Uint8
10-32	Devicenet Revision	SR	All set-ups		TRUE	0	Uint16
10-33	Store Always	[0] Off	1 set-up		TRUE	-	Uint8
10-34	DeviceNet Product Code	SR	1 set-up		TRUE	0	Uint16
10-39	Devicenet F Parameters	0	All set-ups		TRUE	0	Uint32
10-5* CANopen							
10-50	Process Data Config Write.	SR	2 set-ups		TRUE	-	Uint16
10-51	Process Data Config Read.	SR	2 set-ups		TRUE	-	Uint16

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□ **13-** Smart Logic**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
13-0* SLC Settings							
13-00	SL Controller Mode	-	2 set-ups		TRUE	-	Uint8
13-01	Start Event	-	2 set-ups		TRUE	-	Uint8
13-02	Stop Event	-	2 set-ups		TRUE	-	Uint8
13-03	Reset SLC	[0] Do not reset SLC	All set-ups		TRUE	-	Uint8
13-1* Comparators							
13-10	Comparator Operand	-	2 set-ups		TRUE	-	Uint8
13-11	Comparator Operator	-	2 set-ups		TRUE	-	Uint8
13-12	Comparator Value	SR	2 set-ups		TRUE	-3	Int32
13-2* Timers							
13-20	SL Controller Timer	SR	1 set-up		TRUE	-3	TimD
13-4* Logic Rules							
13-40	Logic Rule Boolean 1	-	2 set-ups		TRUE	-	Uint8
13-41	Logic Rule Operator 1	-	2 set-ups		TRUE	-	Uint8
13-42	Logic Rule Boolean 2	-	2 set-ups		TRUE	-	Uint8
13-43	Logic Rule Operator 2	-	2 set-ups		TRUE	-	Uint8
13-44	Logic Rule Boolean 3	-	2 set-ups		TRUE	-	Uint8
13-5* States							
13-51	SL Controller Event	-	2 set-ups		TRUE	-	Uint8
13-52	SL Controller Action	-	2 set-ups		TRUE	-	Uint8

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□ **14-** Special Functions**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
14-0* Inverter Switching							
14-00	Switching Pattern	[1] SFAVM	All set-ups		TRUE	-	Uint8
14-01	Switching Frequency	-	All set-ups		TRUE	-	Uint8
14-03	Overmodulation	[1] On	All set-ups		FALSE	-	Uint8
14-04	PWM Random	[0] Off	All set-ups		TRUE	-	Uint8
14-1* Mains On/Off							
14-10	Mains Failure	[0] No function	All set-ups		FALSE	-	Uint8
14-11	Mains Voltage at Mains Fault	SR	All set-ups		TRUE	0	Uint16
14-12	Function at Mains Imbalance	[0] Trip	All set-ups		TRUE	-	Uint8
14-2* Trip Reset							
14-20	Reset Mode	[0] Manual reset	All set-ups		TRUE	-	Uint8
14-21	Automatic Restart Time	10 s	All set-ups		TRUE	0	Uint16
14-22	Operation Mode	[0] Normal operation	All set-ups		TRUE	-	Uint8
14-23	Typecode Setting	-	2 set-ups		FALSE	-	Uint16
14-25	Trip Delay at Torque Limit	60 s	All set-ups		TRUE	0	Uint8
14-26	Trip Delay at Inverter Fault	SR	All set-ups		TRUE	0	Uint8
14-28	Production Settings	[0] No action	All set-ups		TRUE	-	Uint8
14-29	Service Code	0	All set-ups		TRUE	0	Int32
14-3* Current Limit Ctrl.							
14-30	Current Lim Cont, Proportional Gain	100 %	All set-ups		FALSE	0	Uint16
14-31	Current Lim Contr, Integration Time	0.020 s	All set-ups		FALSE	-3	Uint16
14-4* Energy Optimising							
14-40	VT Level	66 %	All set-ups		FALSE	0	Uint8
14-41	AEO Minimum Magnetisation	40 %	All set-ups		TRUE	0	Uint8
14-42	Minimum AEO Frequency	10 Hz	All set-ups		TRUE	0	Uint8
14-43	Motor Cosphi	SR	All set-ups		TRUE	-2	Uint16
14-5* Environment							
14-50	RFI Filter	[1] On	1 set-up	x	FALSE	-	Uint8
14-52	Fan Control	[0] Auto	All set-ups		TRUE	-	Uint8
14-53	Fan Monitor	[1] Warning	All set-ups		TRUE	-	Uint8
14-55	Output Filter	[0] No Filter	1 set-up		FALSE	-	Uint8

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□ **15-** Drive Information**

Par. No. #	Parameter description	Default value (SR = Size Related)	4-set-up	Change during operation	Conver-sion index	Type
15-0* Operating Data						
15-00 Operating Hours		0 h	All set-ups	FALSE	74	Uint32
15-01 Running Hours		0 h	All set-ups	FALSE	74	Uint32
15-02 kWh Counter		0 kWh	All set-ups	FALSE	75	Uint32
15-03 Power Up's		0	All set-ups	FALSE	0	Uint32
15-04 Over Temp's		0	All set-ups	FALSE	0	Uint16
15-05 Over Volt's		0	All set-ups	FALSE	0	Uint16
15-06 Reset kWh Counter		[0] Do not reset	All set-ups	TRUE	-	Uint8
15-07 Reset Running Hours Counter		[0] Do not reset	All set-ups	TRUE	-	Uint8
15-1* Data Log Settings						
15-10 Logging Source		0	2 set-ups	TRUE	-	Uint16
15-11 Logging Interval		SR	2 set-ups	TRUE	-3	TimD
15-12 Trigger Event		[0] False	1 set-up	TRUE	-	Uint8
15-13 Logging Mode		[0] Log always	2 set-ups	TRUE	-	Uint8
15-14 Samples Before Trigger		50	2 set-ups	TRUE	0	Uint8
15-2* Historic Log						
15-20 Historic Log: Event		0	All set-ups	FALSE	0	Uint8
15-21 Historic Log: Value		0	All set-ups	FALSE	0	Uint32
15-22 Historic Log: Time		0 ms	All set-ups	FALSE	-3	Uint32
15-3* Fault Log						
15-30 Fault Log: Error Code		0	All set-ups	FALSE	0	Uint8
15-31 Fault Log: Value		0	All set-ups	FALSE	0	Int16
15-32 Fault Log: Time		0 s	All set-ups	FALSE	0	Uint32
15-4* Drive Identification						
15-40 FC Type		0	All set-ups	FALSE	0	VisStr[6]
15-41 Power Section		0	All set-ups	FALSE	0	VisStr[20]
15-42 Voltage		0	All set-ups	FALSE	0	VisStr[20]
15-43 Software Version		0	All set-ups	FALSE	0	VisStr[5]
15-44 Ordered Typecode String		0	All set-ups	FALSE	0	VisStr[40]
15-45 Actual Typecode String		0	All set-ups	FALSE	0	VisStr[40]
15-46 Frequency Converter Ordering No		0	All set-ups	FALSE	0	VisStr[8]
15-47 Power Card Ordering No		0	All set-ups	FALSE	0	VisStr[8]
15-48 LCP Id No		0	All set-ups	FALSE	0	VisStr[20]
15-49 SW ID Control Card		0	All set-ups	FALSE	0	VisStr[20]
15-50 SW ID Power Card		0	All set-ups	FALSE	0	VisStr[20]
15-51 Frequency Converter Serial Number		0	All set-ups	FALSE	0	VisStr[10]
15-53 Power Card Serial Number		0	All set-ups	FALSE	0	VisStr[19]

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Par. No. #	Parameter description	Default value	4-set-up	Change during operation	Conver-sion index	Type
15-6* Option Ident						
15-60 Option Mounted	0	All set-ups	FALSE	0	VisStr[30]
15-61 Option SW Version	0	All set-ups	FALSE	0	VisStr[20]
15-62 Option Ordering No	0	All set-ups	FALSE	0	VisStr[8]
15-63 Option Serial No	0	All set-ups	FALSE	0	VisStr[18]
15-70 Option in Slot A	0	All set-ups	FALSE	0	VisStr[30]
15-71 Slot A Option SW Version	0	All set-ups	FALSE	0	VisStr[20]
15-72 Option in Slot B	0	All set-ups	FALSE	0	VisStr[30]
15-73 Slot B Option SW Version	0	All set-ups	FALSE	0	VisStr[20]
15-74 Option in Slot C0	0	All set-ups	FALSE	0	VisStr[30]
15-75 Slot C0 Option SW Version	0	All set-ups	FALSE	0	VisStr[20]
15-76 Option in Slot C1	0	All set-ups	FALSE	0	VisStr[30]
15-77 Slot C1 Option SW Version	0	All set-ups	FALSE	0	VisStr[20]
15-9* Parameter Info						
15-92 Defined Parameters	0	All set-ups	FALSE	0	Uint16
15-93 Modified Parameters	0	All set-ups	FALSE	0	Uint16
15-99 Parameter Metadata	0	All set-ups	FALSE	0	Uint16

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□ **16-** Data Readouts**

Par. No. # Parameter description	Default value (SR = Size Related)	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
16-0* General Status						
16-00Control Word	0	All set-ups		FALSE	0	V2
16-01Reference [Unit]	0.000	All set-ups		FALSE	-3	Int32
16-02Reference %	0.0 %	All set-ups		FALSE	-1	Int16
16-03Status Word	0	All set-ups		FALSE	0	V2
16-05Main Actual Value [%]	0.00 %	All set-ups		FALSE	-2	N2
16-09Custom Readout	0.00	All set-ups		FALSE	-2	Int32
16-1* Motor Status						
16-10Power [kW]	0.00 kW	All set-ups		FALSE	1	Int32
16-11Power [hp]	0.00 hp	All set-ups		FALSE	-2	Int32
16-12Motor Voltage	0.0 V	All set-ups		FALSE	-1	Uint16
16-13Frequency	0.0 Hz	All set-ups		FALSE	-1	Uint16
16-14Motor Current	0.00 A	All set-ups		FALSE	-2	Int32
16-15Frequency [%]	0.00 %	All set-ups		FALSE	-2	N2
16-16Torque [Nm]	0.0 Nm	All set-ups		FALSE	-1	Int16
16-17Speed [RPM]	0 RPM	All set-ups		FALSE	67	Int32
16-18Motor Thermal	0 %	All set-ups		FALSE	0	Uint8
16-19KTY sensor temperature	0 °C	All set-ups		FALSE	100	Int16
16-20Motor Angle	0	All set-ups		TRUE	0	Uint16
16-22Torque [%]	0 %	All set-ups		FALSE	0	Int16
16-3* Drive Status						
16-30DC Link Voltage	0 V	All set-ups		FALSE	0	Uint16
16-32Brake Energy /s	0.000 kW	All set-ups		FALSE	0	Uint32
16-33Brake Energy /2 min	0.000 kW	All set-ups		FALSE	0	Uint32
16-34Heatsink Temp.	0 °C	All set-ups		FALSE	100	Uint8
16-35Inverter Thermal	0 %	All set-ups		FALSE	0	Uint8
16-36Inv. Nom. Current	SR	All set-ups		FALSE	-2	Uint32
16-37Inv. Max. Current	SR	All set-ups		FALSE	-2	Uint32
16-38SL Controller State	0	All set-ups		FALSE	0	Uint8
16-39Control Card Temp.	0 °C	All set-ups		FALSE	100	Uint8
16-40Logging Buffer Full	[0] No	All set-ups		TRUE	-	Uint8
16-5* Ref. & Feedb.						
16-50External Reference	0.0	All set-ups		FALSE	-1	Int16
16-51Pulse Reference	0.0	All set-ups		FALSE	-1	Int16
16-52Feedback [Unit]	0.000	All set-ups		FALSE	-3	Int32
16-53Digi Pot Reference	0.00	All set-ups		FALSE	-2	Int16

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Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
16-6* Inputs & Outputs							
16-60	Digital Input	0	All set-ups		FALSE	0	Uint16
16-61	Terminal 53 Switch Setting	[0] Current	All set-ups		FALSE	-	Uint8
16-62	Analog Input 53	0.000	All set-ups		FALSE	-3	Int32
16-63	Terminal 54 Switch Setting	[0] Current	All set-ups		FALSE	-	Uint8
16-64	Analog Input 54	0.000	All set-ups		FALSE	-3	Int32
16-65	Analog Output 42 [mA]	0.000	All set-ups		FALSE	-3	Int16
16-66	Digital Output [bin]	0	All set-ups		FALSE	0	Int16
16-67	Freq. Input #29 [Hz]	0	All set-ups	x	FALSE	0	Int32
16-68	Freq. Input #33 [Hz]	0	All set-ups		FALSE	0	Int32
16-69	Pulse Output #27 [Hz]	0	All set-ups		FALSE	0	Int32
16-70	Pulse Output #29 [Hz]	0	All set-ups	x	FALSE	0	Int32
16-71	Relay Output [bin]	0	All set-ups		FALSE	0	Int16
16-72	Counter A	0	All set-ups		TRUE	0	Int32
16-73	Counter B	0	All set-ups		TRUE	0	Int32
16-74	Prec. Stop Counter	0	All set-ups		TRUE	0	Uint32
16-75	Analog In X30/11	0.000	All set-ups		FALSE	-3	Int32
16-76	Analog In X30/12	0.000	All set-ups		FALSE	-3	Int32
16-77	Analog Out X30/8 [mA]	0.000	All set-ups		FALSE	-3	Int16
16-8* Fieldbus & FC Port							
16-80	Fieldbus CTW 1	0	All set-ups		FALSE	0	V2
16-82	Fieldbus REF 1	0	All set-ups		FALSE	0	N2
16-84	Comm. Option STW	0	All set-ups		FALSE	0	V2
16-85	FC Port CTW 1	0	All set-ups		FALSE	0	V2
16-86	FC Port REF 1	0	All set-ups		FALSE	0	N2
16-9* Diagnosis Readouts							
16-90	Alarm Word	0	All set-ups		FALSE	0	Uint32
16-91	Alarm word 2	0	All set-ups		FALSE	0	Uint32
16-92	Warning Word	0	All set-ups		FALSE	0	Uint32
16-93	Warning word 2	0	All set-ups		FALSE	0	Uint32
16-94	Ext. Status Word	0	All set-ups		FALSE	0	Uint32

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□ **17-** Motor Feedb.Option**

Par. No. #	Parameter description	Default value (SR = Size related)	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
17-1* Inc. Enc. Interface							
17-10	Signal Type	[1] RS422 (5V TTL)	All set-ups		FALSE	-	Uint8
17-11	Resolution (PPR)	1024	All set-ups		FALSE	0	Uint16
17-2* Abs. Enc. Interface							
17-20	Protocol Selection	[0] None	All set-ups		FALSE	-	Uint8
17-21	Resolution (Positions/Rev)	SR	All set-ups		FALSE	0	Uint32
17-24	SSI Data Length	13	All set-ups		FALSE	0	Uint8
17-25	Clock Rate	SR	All set-ups		FALSE	3	Uint16
17-26	SSI Data Format	[0] Gray code	All set-ups		FALSE	-	Uint8
17-34	HIPERFACE Baudrate	[4] 9600	All set-ups		FALSE	-	Uint8
17-5* Resolver Interface							
17-50	Poles	2	1 set-up		FALSE	0	Uint8
17-51	Input Voltage	7.0 V	1 set-up		FALSE	-1	Uint8
17-52	Input Frequency	10.0 kHz	1 set-up		FALSE	2	Uint8
17-53	Transformation Ratio	0.5	1 set-up		FALSE	-1	Uint8
17-59	Resolver Interface	[0] Disabled	All set-ups		FALSE	-	Uint8
17-6* Monitoring and App.							
17-60	Feedback Direction	[0] Clockwise	All set-ups		FALSE	-	Uint8
17-61	Feedback Signal Monitoring	[1] Warning	All set-ups		TRUE	-	Uint8

□ **17-** Motor Feedb.Option**

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□ 32-** MCO Basic Settings

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
32-0* Encoder 2							
32-00	Incremental Signal Type	[1] RS422 (5V TTL)	2 set-ups		TRUE	-	Uint8
32-01	Incremental Resolution	1024	2 set-ups		TRUE	0	Uint32
32-02	Absolute Protocol	[0] None	2 set-ups		TRUE	-	Uint8
32-03	Absolute Resolution	8192	2 set-ups		TRUE	0	Uint32
32-05	Absolute Encoder Data Length	25	2 set-ups		TRUE	0	Uint8
32-06	Absolute Encoder Clock Frequency	262.000 kHz	2 set-ups		TRUE	0	Uint32
32-07	Absolute Encoder Clock Generation	[1] On	2 set-ups		TRUE	-	Uint8
32-08	Absolute Encoder Cable Length	0 m	2 set-ups		TRUE	0	Uint16
32-09	Encoder Monitoring	[0] Off	2 set-ups		TRUE	-	Uint8
32-10	Rotational Direction	[1] No action	2 set-ups		TRUE	-	Uint8
32-11	User Unit Denominator	1	2 set-ups		TRUE	0	Uint32
32-12	User Unit Numerator	1	2 set-ups		TRUE	0	Uint32
32-3* Encoder 1							
32-30	Incremental Signal Type	[1] RS422 (5V TTL)	2 set-ups		TRUE	-	Uint8
32-31	Incremental Resolution	1024	2 set-ups		TRUE	0	Uint32
32-32	Absolute Protocol	[0] None	2 set-ups		TRUE	-	Uint8
32-33	Absolute Resolution	8192	2 set-ups		TRUE	0	Uint32
32-35	Absolute Encoder Data Length	25	2 set-ups		TRUE	0	Uint8
32-36	Absolute Encoder Clock Frequency	262.000 kHz	2 set-ups		TRUE	0	Uint32
32-37	Absolute Encoder Clock Generation	[1] On	2 set-ups		TRUE	-	Uint8
32-38	Absolute Encoder Cable Length	0 m	2 set-ups		TRUE	0	Uint16
32-39	Encoder Monitoring	[0] Off	2 set-ups		TRUE	-	Uint8
32-40	Encoder Termination	[1] On	2 set-ups		TRUE	-	Uint8
32-6* PID Controller							
32-60	Proportional factor	30	2 set-ups		TRUE	0	Uint32
32-61	Derivative factor	0	2 set-ups		TRUE	0	Uint32
32-62	Integral factor	0	2 set-ups		TRUE	0	Uint32
32-63	Limit Value for Integral Sum	1000	2 set-ups		TRUE	0	Uint16
32-64	PID Bandwidth	1000	2 set-ups		TRUE	0	Uint16
32-65	Velocity Feed-Forward	0	2 set-ups		TRUE	0	Uint32
32-66	Acceleration Feed-Forward	0	2 set-ups		TRUE	0	Uint32
32-67	Max. Tolerated Position Error	20000	2 set-ups		TRUE	0	Uint32
32-68	Reverse Behavior for Slave	[0] Reversing allowed	2 set-ups		TRUE	-	Uint8
32-69	Sampling Time for PID Control	1 ms	2 set-ups		TRUE	-3	Uint16
32-70	Scan Time for Profile Generator	1 ms	2 set-ups		TRUE	-3	Uint8
32-71	Size of the Control Window (Activation)	0	2 set-ups		TRUE	0	Uint32
32-72	Size of the Control Window (Deactiv.)	0	2 set-ups		TRUE	0	Uint32
32-8* Velocity & Accel.							
32-80	Maximum Velocity (Encoder)	1500 RPM	2 set-ups		TRUE	67	Uint32
32-81	Shortest Ramp	1.000 s	2 set-ups		TRUE	-3	Uint32
32-82	Ramp Type	[0] Linear	2 set-ups		TRUE	-	Uint8
32-83	Velocity Resolution	100	2 set-ups		TRUE	0	Uint32
32-84	Default Velocity	50	2 set-ups		TRUE	0	Uint32
32-85	Default Acceleration	50	2 set-ups		TRUE	0	Uint32

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□ **33-** MCO Adv. Settings

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver- sion index	Type
33-0* Home Motion							
33-00	Force HOME	[0] Home not forced	2 set-ups		TRUE	-	Uint8
33-01	Zero Point Offset from Home Pos.	0	2 set-ups		TRUE	0	Int32
33-02	Ramp for Home Motion	10	2 set-ups		TRUE	0	Uint32
33-03	Velocity of Home Motion	10	2 set-ups		TRUE	0	Int32
33-04	Behaviour during HomeMotion	[0] Revers and index	2 set-ups		TRUE	-	Uint8
33-1* Synchronization							
33-10	Synchronization Factor Master (M:S)	1	2 set-ups		TRUE	0	Int32
33-11	Synchronization Factor Slave (M:S)	1	2 set-ups		TRUE	0	Int32
33-12	Position Offset for Synchronization	0	2 set-ups		TRUE	0	Int32
33-13	Accuracy Window for Position Sync.	1000	2 set-ups		TRUE	0	Int32
33-14	Relative Slave Velocity Limit	0 %	2 set-ups		TRUE	0	Uint8
33-15	Marker Number for Master	1	2 set-ups		TRUE	0	Uint16
33-16	Marker Number for Slave	1	2 set-ups		TRUE	0	Uint16
33-17	Master Marker Distance	4096	2 set-ups		TRUE	0	Uint32
33-18	Slave Marker Distance	4096	2 set-ups		TRUE	0	Uint32
33-19	Master Marker Type	[0] Encoder Z positive	2 set-ups		TRUE	-	Uint8
33-20	Slave Marker Type	[0] Encoder Z positive	2 set-ups		TRUE	-	Uint8
33-21	Master Marker Tolerance Window	0	2 set-ups		TRUE	0	Uint32
33-22	Slave Marker Tolerance Window	0	2 set-ups		TRUE	0	Uint32
33-23	Start Behaviour for Marker Sync	[0] Start Function 1	2 set-ups		TRUE	-	Uint16
33-24	Marker Number for Fault	10	2 set-ups		TRUE	0	Uint16
33-25	Marker Number for Ready	1	2 set-ups		TRUE	0	Uint16
33-26	Velocity Filter	0 us	2 set-ups		TRUE	-6	Int32
33-27	Offset Filter Time	0 ms	2 set-ups		TRUE	-3	Uint32
33-28	Marker Filter Configuration	[0] Marker filter 1	2 set-ups		TRUE	-	Uint8
33-29	Filter Time for Marker Filter	0 ms	2 set-ups		TRUE	-3	Int32
33-30	Maximum Marker Correction	0	2 set-ups		TRUE	0	Uint32
33-31	Synchronisation Type	[0] Standard	2 set-ups		TRUE	-	Uint8
33-4* Limit Handling							
33-40	Behaviour atEnd Limit Switch	[0] Call error handler	2 set-ups		TRUE	-	Uint8
33-41	Negative Software End Limit	-500000	2 set-ups		TRUE	0	Int32
33-42	Positive Software End Limit	500000	2 set-ups		TRUE	0	Int32
33-43	Negative Software End Limit Active	[0] Inactive	2 set-ups		TRUE	-	Uint8
33-44	Positive Software End Limit Active	[0] Inactive	2 set-ups		TRUE	-	Uint8
33-45	Time in Target Window	0 ms	2 set-ups		TRUE	-3	Uint8
33-46	Target Window LimitValue	1	2 set-ups		TRUE	0	Uint16
33-47	Size of Target Window	0	2 set-ups		TRUE	0	Uint16

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Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conver-sion index	Type
33-5* I/O Configuration							
33-50	Terminal X57/1 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-51	Terminal X57/2 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-52	Terminal X57/3 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-53	Terminal X57/4 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-54	Terminal X57/5 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-55	Terminal X57/6 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-56	Terminal X57/7 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-57	Terminal X57/8 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-58	Terminal X57/9 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-59	Terminal X57/10 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-60	Terminal X59/1 and X59/2 Mode	[1] Output	2 set-ups		FALSE	-	Uint8
33-61	Terminal X59/1 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-62	Terminal X59/2 Digital Input	[0] No function	2 set-ups		TRUE	-	Uint8
33-63	Terminal X59/1 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-64	Terminal X59/2 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-65	Terminal X59/3 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-66	Terminal X59/4 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-67	Terminal X59/5 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-68	Terminal X59/6 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-69	Terminal X59/7 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-70	Terminal X59/8 Digital Output	[0] No function	2 set-ups		TRUE	-	Uint8
33-8* Global Parameters							
33-80	Activated Program Number	-1	2 set-ups		TRUE	0	Int8
33-81	Power-up State	[1] Motor on	2 set-ups		TRUE	-	Uint8
33-82	Drive Status Monitoring	[1] On	2 set-ups		TRUE	-	Uint8
33-83	Behaviour afterError	[0] Coast	2 set-ups		TRUE	-	Uint8
33-84	Behaviour afterEsc.	[0] Controlled stop	2 set-ups		TRUE	-	Uint8
33-85	MCO Supplied by External 24VDC	[0] No	2 set-ups		TRUE	-	Uint8

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□ 34-** MCO Data Readouts

Par. No. #	Parameter description	Default value	4-set-up	FC 302 only	Change during operation	Conversion index	Type
34-0* PCD Write Par.							
34-01	PCD 1 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-02	PCD 2 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-03	PCD 3 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-04	PCD 4 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-05	PCD 5 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-06	PCD 6 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-07	PCD 7 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-08	PCD 8 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-09	PCD 9 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-10	PCD 10 Write to MCO	0	All set-ups		TRUE	0	Uint16
34-2* PCD Read Par.							
34-21	PCD 1 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-22	PCD 2 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-23	PCD 3 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-24	PCD 4 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-25	PCD 5 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-26	PCD 6 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-27	PCD 7 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-28	PCD 8 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-29	PCD 9 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-30	PCD 10 Read from MCO	0	All set-ups		TRUE	0	Uint16
34-4* Inputs & Outputs							
34-40	Digital Inputs	0	All set-ups		TRUE	0	Uint16
34-41	Digital Outputs	0	All set-ups		TRUE	0	Uint16
34-5* Process Data							
34-50	Actual Position	0	All set-ups		TRUE	0	Int32
34-51	Commanded Position	0	All set-ups		TRUE	0	Int32
34-52	Actual Master Position	0	All set-ups		TRUE	0	Int32
34-53	Slave Index Position	0	All set-ups		TRUE	0	Int32
34-54	Master Index Position	0	All set-ups		TRUE	0	Int32
34-55	Curve Position	0	All set-ups		TRUE	0	Int32
34-56	Track Error	0	All set-ups		TRUE	0	Int32
34-57	Synchronizing Error	0	All set-ups		TRUE	0	Int32
34-58	Actual Velocity	0	All set-ups		TRUE	0	Int32
34-59	Actual Master Velocity	0	All set-ups		TRUE	0	Int32
34-60	Synchronizing Status	0	All set-ups		TRUE	0	Int32
34-61	Axis Status	0	All set-ups		TRUE	0	Int32
34-62	Program Status	0	All set-ups		TRUE	0	Int32
34-7* Diagnosis readouts							
34-70	MCO Alarm Word 1	0	All set-ups		FALSE	0	Uint32
34-71	MCO Alarm Word 2	0	All set-ups		FALSE	0	Uint32

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General Specifications

Mains supply (L1, L2, L3):

Supply voltage .... 200-240 V ±10%
Supply voltage .... FC 301: 380-480 V / FC 302: 380-500 V ±10%
Supply voltage .... FC 302: 525-600 V ±10%
Supply frequency .... 50/60 Hz
Max. imbalance temporary between mains phases .... 3.0 % of rated supply voltage
True Power Factor (λ) .... ≥ 0.9 nominal at rated load
Displacement Power Factor (cos φ) near unity .... (> 0.98)
Switching on input supply L1, L2, L3 (power-ups) ≤ 7.5 kW .... maximum 2 times/min.
Switching on input supply L1, L2, L3 (power-ups) ≥ 11 kW .... maximum 1 time/min.
Environment according to EN60664-1 .... overvoltage category III/pollution degree 2
The unit is suitable for use on a circuit capable of delivering not more than 100.000
RMS symmetrical Amperes, 240/500/600 V maximum.

Motor output (U, V, W):

Output voltage .... 0 - 100% of supply voltage
Output frequency .... FC 301: 0.2 - 1000 Hz / FC 302: 0 - 1000 Hz
Switching on output .... Unlimited
Ramp times .... 0.01 - 3600 sec.

Torque characteristics:

Starting torque (Constant torque) .... maximum 160% for 1 min.*
Starting torque .... maximum 180% up to 0.5 sec.*
Overload torque (Constant torque) .... maximum 160% for 1 min.*
Percentage relates to FC 300's nominal torque.

Digital inputs:

Programmable digital inputs .... FC 301: 4 (5) / FC 302: 4 (6)
Terminal number .... 18, 19, 27 [1)], 29 [4)], 32, 33,
Logic .... PNP or NPN
Voltage level .... 0 - 24 V DC
Voltage level, logic'0' PNP .... < 5 V DC
Voltage level, logic'1' PNP .... > 10 V DC
Voltage level, logic '0' NPN [2)] .... > 19 V DC
Voltage level, logic '1' NPN [2)] .... < 14 V DC

— General Specifications —

Maximum voltage on input .... 28 V DC
Input resistance, R_i .... approx. 4 kΩ

Safe stop Terminal 37[4]):
Terminal 37 is fixed PNP logic

Voltage level .... 0 - 24 V DC
Voltage level, logic'0' PNP .... < 4 V DC
Voltage level, logic'1' PNP .... >20 V DC
Nominal input current at 24 V .... 50 mA rms
Nominal input current at 20 V .... 60 mA rms
Input capacitance .... 400 nF
All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.
1) Terminals 27 and 29 can also be programmed as output.
2) Except safe stop input Terminal 37.
3) Terminal 37 is only available in FC 302 and FC 301 A1 with Safe Stop. It can only be used as safe stop input.
Terminal 37 is suitable for category 3 installations according to EN 954-1 (safe stop according to category 0
EN 60204-1) as required by the EU Machinery Directive 98/37/EC. Terminal 37 and the Safe Stop function are
designed in conformance with EN 60204-1, EN 50178, EN 61800-2, EN 61800-3, and EN 954-1. For correct
and safe use of the Safe Stop function follow the related information and instructions in the Design Guide.
*4) FC 302 and FC 301 A1with Safe Stop only.*

Analog inputs:

Number of analog inputs 2
Terminal number 53, 54
Modes .... Voltage or current
Mode select .... Switch S201 and switch S202
Voltage mode .... Switch S201/switch S202 = OFF (U)
Voltage level .... FC 301: 0 to + 10 / FC 302: -10 to +10 V (scaleable)
Input resistance, R_i .... approx. 10 kΩ
Max. voltage .... ± 20 V
Current mode .... Switch S201/switch S202 = ON (I)
Current level .... 0/4 to 20 mA (scaleable)
Input resistance, R_i .... approx. 200 Ω
Max. current .... 30 mA
Resolution for analog inputs .... 10 bit (+ sign)
Accuracy of analog inputs .... Max. error 0.5% of full scale
Bandwidth .... FC 301: 20 Hz / FC 302: 100 Hz
The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.
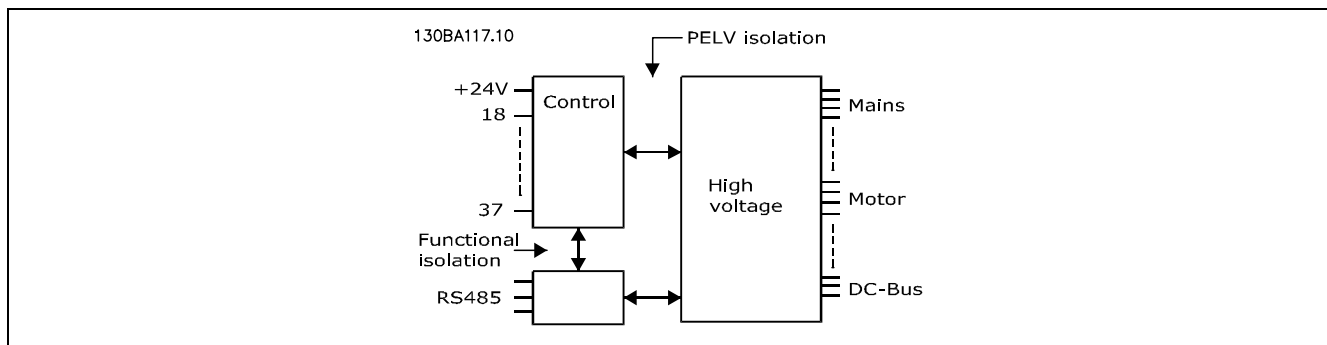
— General Specifications —

Pulse/encoder inputs:

Programmable pulse/encoder inputs	2/1
Terminal number pulse/encoder	29, 33[1] / 18, 32, 33[2]
Max. frequency at terminal 18, 29, 32, 33	110 kHz (Push-pull driven)
Max. frequency at terminal 18, 29, 32, 33	5 kHz (open collector)
Min. frequency at terminal 18, 29, 32, 33	4 Hz
Voltage level	see section on Digital input
Maximum voltage on input	28 V DC
Input resistance, R_i	approx. 4 kΩ
Pulse input accuracy (0.1 - 1 kHz)	Max. error: 0.1% of full scale
Encoder input accuracy (1 - 110 kHz)	Max. error: 0.05 % of full scale

The pulse and encoder inputs (terminals 18, 29, 32, 33) are galvanically isolated from the
supply voltage (PELV) and other high-voltage terminals.
1) Pulse inputs are 29 and 33
2) Encoder inputs: 32 = A, and 33 = B

Digital output:

Programmable digital/pulse outputs	2
Terminal number	27, 29 [1]
Voltage level at digital/frequency output	0 - 24 V
Max. output current (sink or source)	40 mA
Max. load at frequency output	1 kΩ
Max. capacitive load at frequency output	10 nF
Minimum output frequency at frequency output	0 Hz
Maximum output frequency at frequency output	32 kHz
Accuracy of frequency output	Max. error: 0.1 % of full scale
Resolution of frequency outputs	12 bit

1) Terminal 27 and 29 can also be programmed as input.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Analog output:

Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4 - 20 mA
Max. load to common at analog output	500 Ω
Accuracy on analog output	Max. error: 0.5 % of full scale
Resolution on analog output	12 bit

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, 24 V DC output:

Terminal number	12, 13
Max. load	FC 301: 130 mA / FC 302: 200 mA

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same
potential as the analog and digital inputs and outputs.

Control card, 10 V DC output:

Terminal number	50
Output voltage	10.5 V ±0.5 V
Max. load	15 mA

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

— General Specifications —

Control card, RS 485 serial communication:

Terminal number	68 (P,TX+, RX+), 69 (N,TX-, RX-)
Terminal number 61	Common for terminals 68 and 69

The RS 485 serial communication circuit is functionally separated from other central circuits
and galvanically isolated from the supplier voltage (PELV).

Control card, USB serial communication:

USB standard	1.1 (Full speed)
USB plug	USB type B "device" plug

Connection to PC is carried out via a standard host/device USB cable.
The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.
The USB ground connection is not galvanically isolated from protection earth. Use only isolated
laptop as PC connection to the USB connector on FC 300 drive.

Relay outputs:

Programmable relay outputs	FC 301 ≤ 7.5 kW: 1 / FC 301 ≥ 11 kW: 2 / FC 302 all kW: 2
Relay 01 Terminal number	1-3 (break), 1-2 (make)
Max. terminal load (AC-1)[1] on 1-3 (NC), 1-2 (NO) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15)[1] (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1)[1] on 1-2 (NO), 1-3 (NC) (Resistive load)	60 V DC, 1A
Max. terminal load (DC-13)[1] (Inductive load)	24 V DC, 0.1A
Relay 02 (FC 302 only) Terminal number	4-6 (break), 4-5 (make)
Max. terminal load (AC-1)[1] on 4-5 (NO) (Resistive load)	400 V AC, 2 A
Max. terminal load (AC-15)[1] on 4-5 (NO) (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1)[1] on 4-5 (NO) (Resistive load)	80 V DC, 2 A
Max. terminal load (DC-13)[1] on 4-5 (NO) (Inductive load)	24 V DC, 0.1A
Max. terminal load (AC-1)[1] on 4-6 (NC) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15)[1] on 4-6 (NC) (Inductive load @ cosφ 0.4)	240 V AC, 0.2A
Max. terminal load (DC-1)[1] on 4-6 (NC) (Resistive load)	50 V DC, 2 A
Max. terminal load (DC-13)[1] on 4-6 (NC) (Inductive load)	24 V DC, 0.1 A
Min. terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO)	24 V DC 10 mA, 24 V AC 20 mA
Environment according to EN 60664-1	overvoltage category III/pollution degree 2

1) IEC 60947 part 4 and 5
The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).

Cable lengths and cross sections:

Max. motor cable length, screened/armoured	FC 301: 50 m / FC 302: 150 m
Max. motor cable length, unscreened/unarmoured	FC 301: 75 m / FC 302: 300 m
Max. cross section to motor, mains, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (0.25 kW - 7.5 kW)	4 mm² / 10 AWG
Max. cross section to motor, mains, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (11-15 kW)	16 mm² / 6 AWG
Max. cross section to motor, mains, load sharing and brake (see section Electrical Data in the FC 300 Design Guide MG.33.BX.YY for more information), (18.5-22 kW)	35 mm² / 2 AWG
Maximum cross section to control terminals, rigid wire	1.5 mm²/16 AWG (2 x 0.75 mm²)
Maximum cross section to control terminals, flexible cable	1 mm²/18 AWG
Maximum cross section to control terminals, cable with enclosed core	0.5 mm²/20 AWG
Minimum cross section to control terminals	0.25 mm²

Control card performance:

Scan interval	FC 301: 5 ms / FC 302: 1 ms

— General Specifications —

Control characteristics:

Resolution of output frequency at 0 - 1000 Hz	FC 301: +/- 0.013 Hz / FC 302: +/- 0.003 Hz
Repeat accuracy of *Precise start/stop* (terminals 18, 19)	FC 301: ≤ ± 1ms / FC 302: ≤ ± 0.1 msec
System response time (terminals 18, 19, 27, 29, 32, 33)	FC 301: ≤ 10 ms / FC 302: ≤ 2 ms
Speed control range (open loop)	1:100 of synchronous speed
Speed control range (closed loop)	1:1000 of synchronous speed
Speed accuracy (open loop)	30 - 4000 rpm: Maximum error of ±8 rpm
Speed accuracy (closed loop)	0 - 6000 rpm: Maximum error of ±0.15 rpm

All control characteristics are based on a 4-pole asynchronous motor

Surroundings:

Enclosure ≤ 7.5 kW	IP 20, IP 55
Enclosure ≥ 11 kW	IP 21, IP 55
Enclosure kit available ≤ 7.5 kW	IP21/TYPE 1/IP 4X top
Vibration test	1.0 g
Max. relative humidity .... 5% - 95%(IEC 721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 60068-2-43	class $H_2$5
Ambient temperature .... Max. 50 °C (24-hour average maximum 45 °C)

Derating for high ambient temperature, see special conditions in the Design Guide

Minimum ambient temperature during full-scale operation	0 °C
Minimum ambient temperature at reduced performance	- 10 °C
Temperature during storage/transport	-25 - +65/70 °C
Maximum altitude above sea level	1000 m

Derating for high altitude, see special conditions in the Design Guide

EMC standards, Emission	EN 61800-3, EN 61000-6-3/4, EN 55011
EMC standards, Immunity	EN 61800-3, EN 61000-6-1/2,

EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6

See section on special conditions in the Design Guide

Protection and Features:

- Electronic thermal motor protection against overload.
- Temperature monitoring of the heatsink ensures that the frequency converter trips if the temperature reaches 95 °C ± 5°C. An overload temperature cannot be reset until the temperature of the heatsink is below 70 °C ± 5°C (Guideline - these temperatures may vary for different power sizes, enclosures etc.).
- The frequency converter is protected against short-circuits on motor terminals U, V, W.
- If a mains phase is missing, the frequency converter trips or issues a warning (depending on the load).
- Monitoring of the intermediate circuit voltage ensures that the frequency converter trips if the intermediate circuit voltage is too low or too high.
- The frequency converter is protected against earth faults on motor terminals U, V, W.

Hz
V
A
IP
°C
Ω

Warnings and Alarms

□ **Warnings/Alarm Messages**

A warning or an alarm is signalled by the relevant LED on the front of the frequency converter and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the frequency converter will have tripped. Alarms must be reset to restart operation once their cause has been rectified. This may be done in three ways:

1. By using the [RESET] control button on the LCP control panel.
2. Via a digital input with the "Reset" function.
3. Via serial communication/optional fieldbus.

NB!:
After a manual reset using the [RESET] button on the LCP, the [AUTO ON] button must be pressed to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also table on following page).

Alarms that are trip-locked offer additional protection, meaning that the mains supply must be switched off before the alarm can be reset. After being switched back on, the FC 300 is no longer blocked and may be reset as described above once the cause has been rectified.

Alarms that are not trip-locked can also be reset using the automatic reset function in parameters 14-20 (Warning: automatic wake-up is possible!)

If a warning and alarm is marked against a code in the table on the following page, this means that either a warning occurs before an alarm, or else that you can specify whether it is a warning or an alarm that is to be displayed for a given fault.

This is possible, for instance, in parameters 1-90 *Motor Thermal Protection.* After an alarm or trip, the motor carries on coasting, and the alarm and warning flash on the FC 300. Once the problem has been rectified, only the alarm continues flashing.

— Warnings and Alarms —

Alarm/Warning code list

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
1	10 Volts low	X			
2	Live zero error	(X)	(X)		6-01
3	No motor	(X)			1-80
4	Mains phase loss	(X)	(X)	(X)	14-12
5	DC link voltage high	X			
6	DC link voltage low	X			
7	DC over voltage	X	X		
8	DC under voltage	X	X		
9	Inverter overloaded	X	X		
10	Motor ETR over temperature	(X)	(X)		1-90
11	Motor thermistor over temperature	(X)	(X)		1-90
12	Torque limit	X	X		
13	Over Current	X	X	X	
14	Earth fault	X	X	X	
15	Hardware mismatch		X	X	
16	Short Circuit		X	X	
17	Control word timeout	(X)	(X)		8-04
24	FC Fan Fault	X			14-53
25	Brake resistor short-circuited	X			
26	Brake resistor power limit	(X)	(X)		2-13
27	Brake chopper short-circuited	X	X		
28	Brake check	(X)	(X)		2-15
29	Power board over temp	X	X	X	
30	Motor phase U missing	(X)	(X)	(X)	4-58
31	Motor phase V missing	(X)	(X)	(X)	4-58
32	Motor phase W missing	(X)	(X)	(X)	4-58
33	Inrush fault		X	X	
34	Fieldbus communication fault	X	X		
38	Internal fault		X	X	
47	24 V supply low	X	X	X	
48	1.8 V supply low		X	X	
49	Speed limit	X			
50	AMA calibration failed		X		
51	AMA check U_{nom} and I_{nom}		X		
52	AMA low I_{nom}		X		
53	AMA motor too big		X		
54	AMA motor too small		X		
55	AMA parameter out of range		X		
56	AMA interrupted by user		X		
57	AMA timeout		X		
58	AMA internal fault	X	X		
59	Current limit	X			
61	Tracking Error	(X)	(X)		4-30
62	Output Frequency at Maximum Limit	X			
63	Mechanical Brake Low		(X)		2-20
64	Voltage Limit	X			
65	Control Board Over-temperature	X	X	X	
66	Heat sink Temperature Low	X			
67	Option Configuration has Changed		X		
68	Safe Stop Activated		X		
70	Illegal FC configuration			X	
80	Drive Initialised to Default Value		X		
90	Encoder Loss	(X)	(X)		17-61
91	Analogue input 54 wrong settings			X	S202
250	New spare part			X	14-23

(X) Dependent on parameter

LED indication	
Warning	yellow
Alarm	flashing red
Trip locked	yellow and red

— Warnings and Alarms —

Description of Alarm Word, Warning Word and extended Status Word

Bit	Hex	Dec	AlarmWord	WarningWord	ExtendedStatusWord
0	00000001	1	Brake Check	Brake Check	Ramping
1	00000002	2	Pwr. Card Temp	Pwr. Card Temp	AMA Running
2	00000004	4	Earth Fault	Earth Fault	Start CW/CCW
3	00000008	8	Ctrl.Card Temp	Ctrl.Card Temp	Slow Down
4	00000010	16	Ctrl. Word TO	Ctrl. Word TO	Catch Up
5	00000020	32	Over Current	Over Current	Feedback High
6	00000040	64	Torque Limit	Torque Limit	Feedback Low
7	00000080	128	Motor Th Over	Motor Th Over	Output Current High
8	00000100	256	Motor ETR Over	Motor ETR Over	Output Current Low
9	00000200	512	Inverter Overld.	Inverter Overld.	Output Freq High
10	00000400	1024	DC under Volt	DC under Volt	Output Freq Low
11	00000800	2048	DC over Volt	DC over Volt	Brake Check OK
12	00001000	4096	Short Circuit	DC Voltage Low	Braking Max
13	00002000	8192	Inrush Fault	DC Voltage High	Braking
14	00004000	16384	Mains ph. Loss	Mains ph. Loss	Out of Speed Range
15	00008000	32768	AMA Not OK	No Motor	OVC Active
16	00010000	65536	Live Zero Error	Live Zero Error	
17	00020000	131072	Internal Fault	10V Low	
18	00040000	262144	Brake Overload	Brake Overload	
19	00080000	524288	U phase Loss	Brake Resistor	
20	00100000	1048576	V phase Loss	Brake IGBT	
21	00200000	2097152	W phase Loss	Speed Limit	
22	00400000	4194304	Fieldbus Fault	Fieldbus Fault	
23	00800000	8388608	24 V Supply Low	24V Supply Low	
24	01000000	16777216	Mains Failure	Mains Failure	
25	02000000	33554432	1.8V Supply Low	Current Limit	
26	04000000	67108864	Brake Resistor	Low Temp	
27	08000000	134217728	Brake IGBT	Voltage Limit	
28	10000000	268435456	Option Change	Unused	
29	20000000	536870912	Drive Initialised	Unused	
30	40000000	1073741824	Safe Stop	Unused	
31	80000000	2147483648	Mech. brake low	Extended Status Word	

The alarm words, warning words and extended status words can be read out via serial bus or optional fieldbus for diagnose. See also par. 16-90, 16-92 and 16-94.

WARNING 1
10 Volts low:
The 10 V voltage from terminal 50 on the control card is below 10 V.
Remove some of the load from terminal 50, as the 10 V supply is overloaded. Max. 15 mA or minimum 590 Ω.

WARNING/ALARM 2
Live zero error:
The signal on terminal 53 or 54 is less than 50% of the value set in par. 6-10, 6-12, 6-20, or 6-22 respectively.

WARNING/ALARM 3
No motor:
No motor has been connected to the output of the frequency converter.

WARNING/ALARM 4
Mains phase loss:
A phase is missing on the supply side, or the mains voltage imbalance is too high.
This message also appears in case of a fault in the input rectifier on the frequency converter.
Check the supply voltage and supply currents to the frequency converter.

WARNING 5
DC link voltage high:
The intermediate circuit voltage (DC) is higher than the overvoltage limit of the control system. The frequency converter is still active.

— Warnings and Alarms —

WARNING 6
DC link voltage low
The intermediate circuit voltage (DC) is below the undervoltage limit of the control system. The frequency converter is still active.

WARNING/ALARM 7
DC over voltage:
If the intermediate circuit voltage exceeds the limit, the frequency converter trips after a time.
Possible corrections:

Connect a brake resistor
Extend the ramp time
Activate functions in par. 2-10
Increase par. 14-26

Connect a brake resistor. Extend the ramp time

Alarm/warning limits:			
FC 300 Series	3 x 200 - 240 V [VDC]	3 x 380 - 500 V [VDC]	3 x 525 - 600 V [VDC]
Undervoltage	185	373	532
Voltage warning low	205	410	585
Voltage warning high (w/o brake - w/brake)	390/405	810/840	943/965
Overvoltage	410	855	975

The voltages stated are the intermediate circuit voltage of the FC 300 with a tolerance of ± 5 %. The corresponding mains voltage is the intermediate circuit voltage (DC-link) divided by 1.35

WARNING/ALARM 8
DC under voltage:
If the intermediate circuit voltage (DC) drops below the "voltage warning low" limit (see table above), the frequency converter checks if 24 V backup supply is connected.
If no 24 V backup supply is connected, the frequency converter trips after a given time depending on the unit.
To check whether the supply voltage matches the frequency converter, see *General Specifications*.

WARNING/ALARM 9
Inverter overloaded:
The frequency converter is about to cut out because of an overload (too high current for too long). The

counter for electronic, thermal inverter protection gives a warning at 98% and trips at 100%, while giving an alarm. You <u>cannot</u> reset the frequency converter until the counter is below 90%.
The fault is that the frequency converter is overloaded by more than 100% for too long.

WARNING/ALARM 10
Motor ETR over temperature:
According to the electronic thermal protection (ETR), the motor is too hot. You can choose if you want the frequency converter to give a warning or an alarm when the counter reaches 100% in par. 1-90. The fault is that the motor is overloaded by more than 100% for too long. Check that the motor par. 1-24 is set correctly.

WARNING/ALARM 11
Motor thermistor over temp:
The thermistor or the thermistor connection is disconnected. You can choose if you want the frequency converter to give a warning or an alarm when the counter reaches 100% in par. 1-90. Check that the thermistor is connected correctly between terminal 53 or 54 (analog voltage input) and terminal 50 (+ 10 Volts supply), or between terminal 18 or 19 (digital input PNP only) and terminal 50. If a KTY sensor is used, check for correct connection between terminal 54 and 55.

WARNING/ALARM 12
Torque limit:
The torque is higher than the value in par. 4-16 (in motor operation) or the torque is higher than the value in par. 4-17 (in regenerative operation).

WARNING/ALARM 13
Over Current:
The inverter peak current limit (approx. 200% of the rated current) is exceeded. The warning will last approx. 8-12 sec., then the frequency converter trips and issues an alarm. Turn off the frequency converter and check if the motor shaft can be turned and if the motor size matches the frequency converter.
If extended mechanical brake control is selected, trip can be reset externally.

ALARM 14
Earth fault:
There is a discharge from the output phases to earth, either in the cable between the frequency converter and the motor or in the motor itself.
Turn off the frequency converter and remove the earth fault.

— Warnings and Alarms —

ALARM 15
In-complete hardware:
A fitted option is not handled by the present control board (hardware or software).

ALARM 16
Short-circuit:
There is short-circuiting in the motor or on the motor terminals.
Turn off the frequency converter and remove the short-circuit.

WARNING/ALARM 17
Control word timeout:
There is no communication to the frequency converter.
The warning will only be active when par. 8-04 is NOT set to *OFF*.
If par. 8-04 is set to *Stop* and *Trip*, a warning appears and the frequency converter ramps down until it trips, while giving an alarm.
par. 8-03 *Control word Timeout Time* could possibly be increased.

WARNING 24
FC fan fault:
The fan warning function is an extra protection function that checks if the fan is running / mounted. The fan warning can be disabled in *Fan Monitor*, par. 14-53, (set to [0] Disabled).

WARNING 25
Brake resistor short-circuited:
The brake resistor is monitored during operation. If it short-circuits, the brake function is disconnected and the warning appears. The frequency converter still works, but without the brake function. Turn off the frequency converter and replace the brake resistor (see par. 2-15 *Brake Check*.

ALARM/WARNING 26
Brake resistor power limit:
The power transmitted to the brake resistor is calculated as a percentage, as a mean value over the last 120 s, on the basis of the resistance value of the brake resistor (par. 2-11) and the intermediate circuit voltage. The warning is active when the dissipated braking power is higher than 90%. If *Trip* [2] has been selected in par. 2-13, the frequency converter cuts out and issues this alarm, when the dissipated braking power is higher than 100%.

WARNING 27
Brake chopper fault:
The brake transistor is monitored during operation and if it short-circuits, the brake function disconnects and the warning comes up. The frequency converter

is still able to run, but since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive.
Turn off the frequency converter and remove the brake resistor.

! Warning: There is a risk of substantial power being transmitted to the brake resistor if the brake transistor is short-circuited.

ALARM/WARNING 28
Brake check failed:
Brake resistor fault: the brake resistor is not connected/working.

ALARM 29
Drive over temperature:
If the enclosure is IP 20 or IP 21/TYPE 1, the cut-out temperature of the heat-sink is 95 ^{o}C $\pm$5 ^{o}C. The temperature fault cannot be reset, until the temperature of the heatsink is below 70 ^{o}C $\pm$5 ^{o}C. The fault could be:

- Ambient temperature too high
- Too long motor cable

ALARM 30
Motor phase U missing:
Motor phase U between the frequency converter and the the motor is missing.
Turn off the frequency converter and check motor phase U.

ALARM 31
Motor phase V missing:
Motor phase V between the frequency converter and the motor is missing.
Turn off the frequency converter and check motor phase V.

ALARM 32
Motor phase W missing:
Motor phase W between the frequency converter and the motor is missing.
Turn off the frequency converter and check motor phase W.

ALARM 33
Inrush fault:
Too many powerups have occured within a short time period. See the chapter *General Specifications* for the allowed number of powerups within one minute.

— Warnings and Alarms —

WARNING/ALARM 34
Fieldbus communication fault:
The fieldbus on the communication option card is not working.

WARNING 35
Out of frequency range:
This warning is active if the output frequency has reached its *Warning speed low* (par. 4-52) or *Warning speed high* (par. 4-53). If the frequency converter is in *Process control, closed loop* (par. 1-00), the warning is active in the display. If the frequency converter is not in this mode bit 008000 Out of *frequency range* in extended status word is active but there is no warning in the display.

ALARM 38
Internal fault:
By this alarm it may be necessary to contact your Danfoss supplier. Some typical alarm messages:

0	The serial port cannot be initialized. Serious hardware failure
256	The power E^{2}PROM data is defect or too old
512	The control board E^{2}PROM data is defect or too old
513	Communication time out Reading E^{2}PROM data
514	Communication time out Reading E^{2}PROM data
515	The Application Orientated Control cannot recognize the E^{2}Prom data
516	Cannot write write to the E^{2}PROM because a write command is on progress
517	The write command is under time out
518	Failure in the E^{2}Prom
519	Missing or invalid BarCode data in E^{2}Prom 1024 – 1279 CAN telegram cannot be sent. (1027 indicate a possible hardware failure)
1281	Digital Signal Processor flash time-out
1282	Power micro software version mismatch
1283	Power E^{2}PROM data version mismatch
1284	Cannot read Digital Signal Processor software version
1299	Option SW in slot A is too old
1300	Option SW in slot B is too old
1301	Option SW in slot C0 is too old
1302	Option SW in slot C1 is too old
1315	Option SW in slot A is not supported (not allowed)
1316	Option SW in slot B is not supported (not allowed)
1317	Option SW in slot C0 is not supported (not allowed)
1318	Option SW in slot C1 is not supported (not allowed)
1536	An exception in the Application Orientated Control is registered. Debug information written in LCP
1792	DSP watchdog is active. Debugging of power part data Motor Orientated Control data not transferred correctly
2049	Power data restarted
2315	Missing SW version from power unit
2816	Stack overflow Control board module
2817	Scheduler slow tasks
2818	Fast tasks
2819	Parameter thread
2820	LCP stack overflow
2821	Serial port overflow
2822	USB port overflow
3072-5122	Parameter value is outside its limits. Perform a initialization. Parameter number causing the alarm: Subtract the code from 3072. Ex Error code 3238: 3238-3072 = 166 is outside the limit
5123	Option in slot A: Hardware incompatible with Control board hardware
5124	Option in slot B: Hardware incompatible with Control board hardware
5125	Option in slot C0: Hardware incompatible with Control board hardware
5126	Option in slot C1: Hardware incompatible with Control board hardware
5376-6231	Out of memory

WARNING 47
24 V supply low:
The external 24 V DC backup power supply may be overloaded, otherwise Contact your Danfoss supplier.

— Warnings and Alarms —

WARNING 48
1.8 V supply low:
Contact your Danfoss supplier.

WARNING 49
Speed limit:
The speed is not within the specified range
in par. 4-11 and par. 4-13..

ALARM 50
AMA calibration failed:
Contact your Danfoss supplier.

ALARM 51
AMA check Unom and Inom:
The setting of motor voltage, motor current,
and motor power is presumably wrong.
Check the settings.

ALARM 52
AMA low Inom:
The motor current is too low. Check the settings.

ALARM 53
AMA motor too big:
The motor is too big for the AMA to be carried out.

ALARM 54
AMA motor too small:
The motor is too big for the AMA to be carried out.

ALARM 55
AMA par. out of range:
The par. values found from the motor are
outside acceptable range.

ALARM 56
AMA interrupted by user:
The AMA has been interrupted by the user.

ALARM 57
AMA timeout:
Try to start the AMA again a number of times,
until the AMA is carried out. Please note that
repeated runs may heat the motor to a level where
the resistance Rs and Rr are increased. In most
cases, however, this is not critical.

ALARM 58
AMA internal fault:
Contact your Danfoss supplier.

WARNING 59
Current limit:
Contact your Danfoss supplier.

WARNING 61
Encoder loss:
Contact your Danfoss supplier.

WARNING 62
Output Frequency at Maximum Limit:
The output frequency is higher than the
value set in par. 4-19

ALARM 63
Mechanical Brake Low:
The actual motor current has not exceeded
the "release brake" current within the "Start
delay" time window.

WARNING 64
Voltage Limit:
The load and speed combination demands a motor
voltage higher than the actual DC link voltage.

WARNING/ALARM/TRIP 65
Control Card Over Temperature:
Control card over temperature: The cut-out
temperature of the control card is 80° C.

WARNING 66
Heatsink Temperature Low:
The heat sink temperature is measured as 0° C. This
could indicate that the temperature sensor is defect
and thus the fan speed is increased to the maximum
in case the power part or control card is very hot.

ALARM 67
Option Configuration has Changed:
One or more options has either been added or
removed since the last power-down.

ALARM 68
Safe Stop Activated:
Safe Stop has been activated. To resume normal
operation, apply 24 V DC to terminal 37, then
send a reset signal (via Bus, Digital I/O, or by
pressing [RESET]). For correct and safe use of the
Safe Stop function follow the related information
and instructions in the Design Guide

ALARM 70
Illegal FC Configuration:
Actual combination of control board and
power board is illegal.

ALARM 80
Drive Initialised to Default Value:
Parameter settings are initialised to default setting
after a manual (three-finger) reset.

ALARM 91
Analogue Input 54 Wrong Settings:
Switch S202 has to be set in position OFF
(voltage input) when a KTY sensor is connected
to analogue input terminal 54.

ALARM 250

New Spare Part:

The power or Switch Mode Power Supply has been exchanged. The frequency converter type code must be restored in the E^2PROM. Select the correct type code in Par 14-23 according to the label on unit. Remember to select 'Save to EEPROM' to complete.

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